

[https://www.sli.do/
#073374](https://www.sli.do/#073374)



AI Frontier (I) – On-site Rebar Inspection using Deep Learning and Digital Twin

Learning Objectives

- Learn how we use deep learning to conduct rebar inspection.
- Learn the techniques we use to make the deep learning model perform better.

Rebar Inspection using Deep Learning

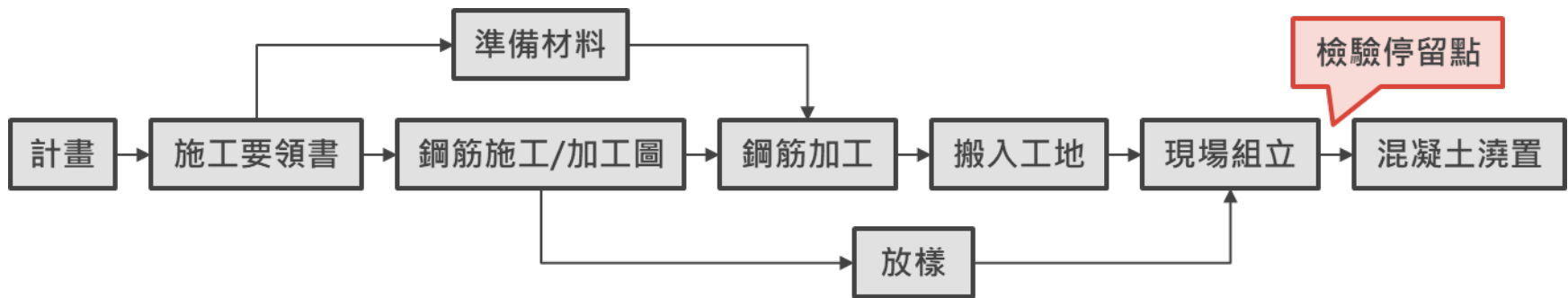
Rebar Project Construction Inspection Process

• Current inspection method

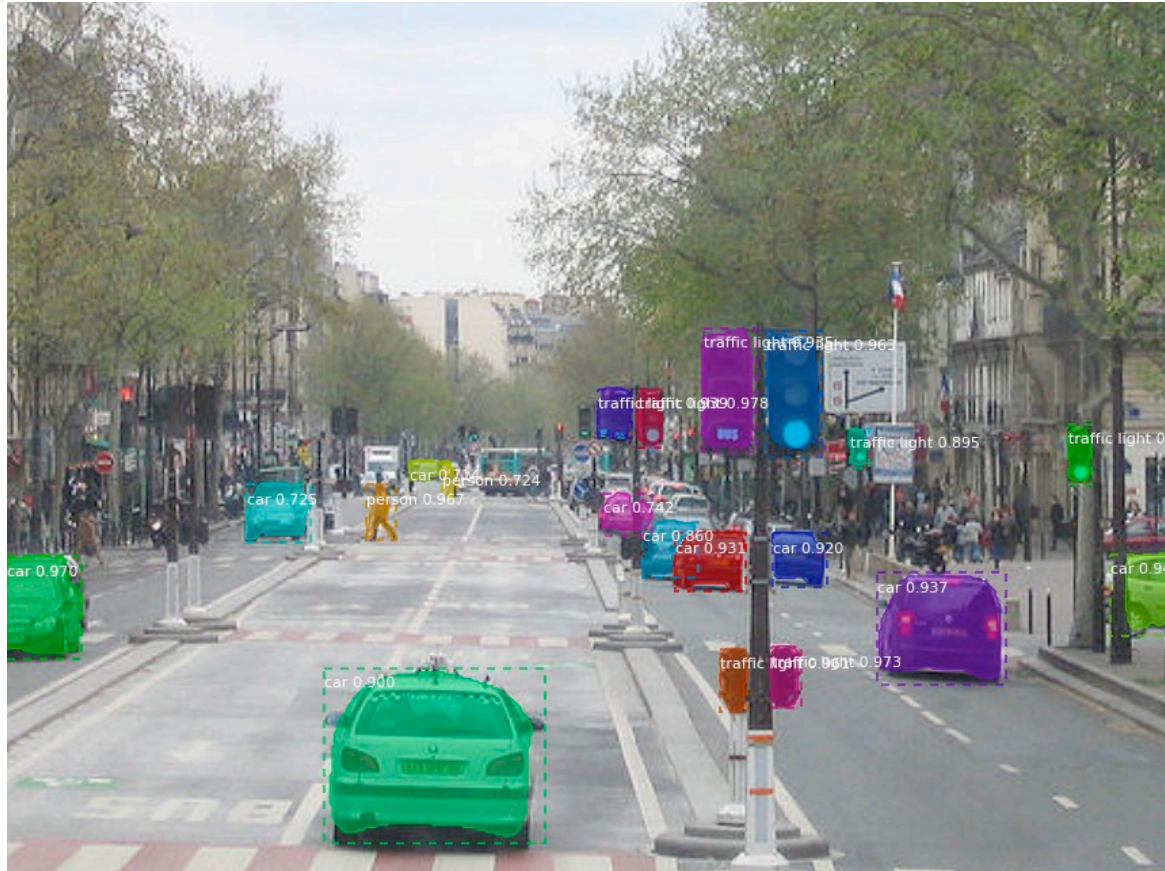
- Tape measure
- Construction drawing
- Hard-copy record

• Issues

- Large number of rebars
- Difficult measurement
- Timeliness

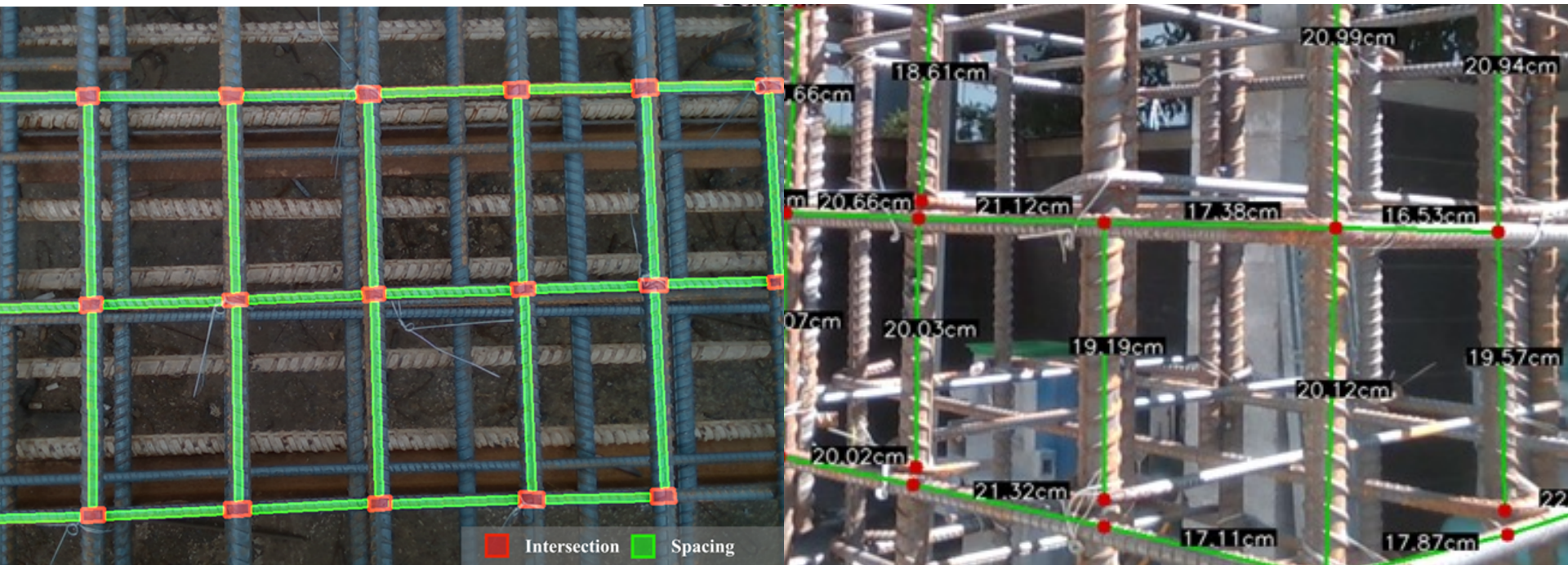


Instance Segmentation (Pixel Level Recognition) Mask R-CNN



Kaiming He et al. (2018). Mask R-CNN. [arXiv:1703.06870](https://arxiv.org/abs/1703.06870)

Instance Segmentation (Pixel Level Recognition) Mask R-CNN

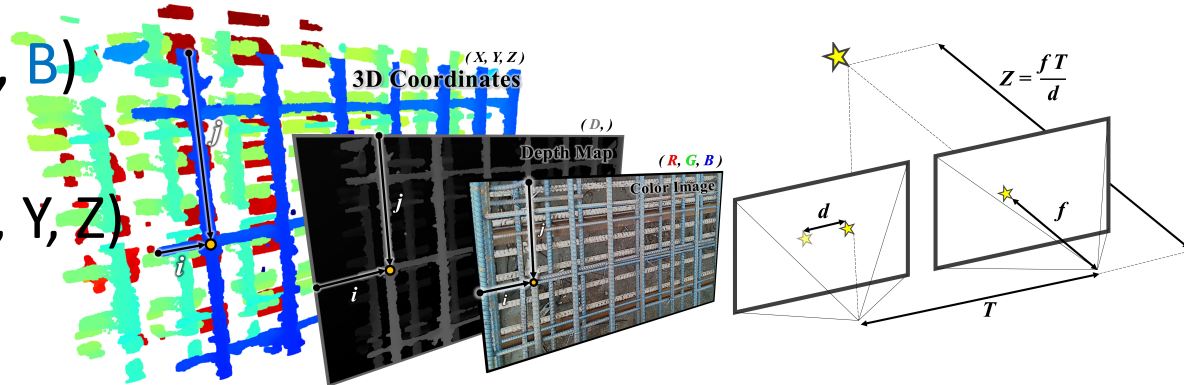


Kaiming He et al. (2018). Mask R-CNN. arXiv:1703.06870

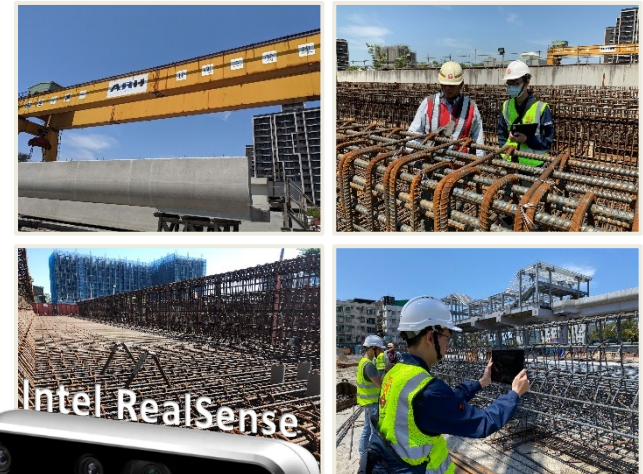
Data Collection

- **RGB-D data**

- Color image (R, G, B)
- Depth map (D)
- 3D point cloud (X, Y, Z)

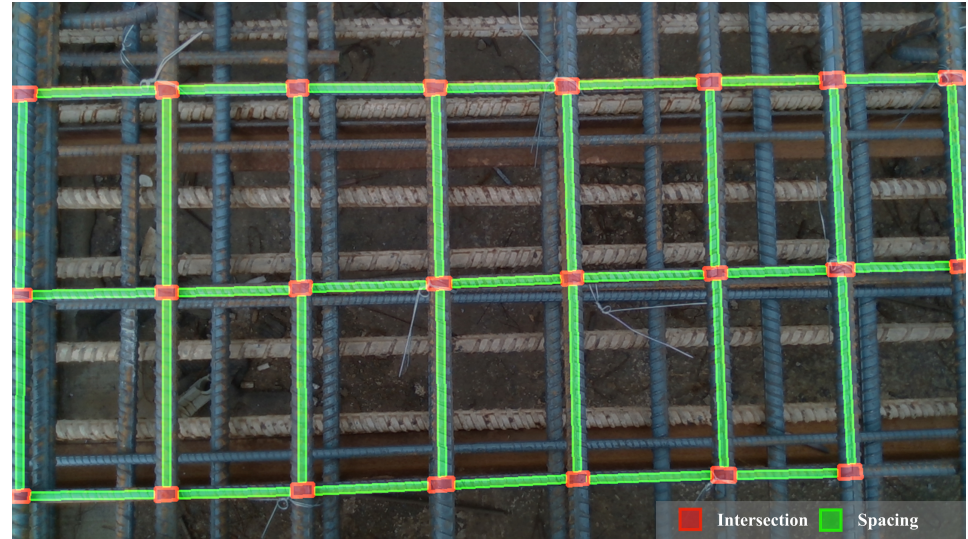


| Collected Date | Rebar assembly | Training set | Testing set |
|----------------|------------------|--------------|-------------|
| 2019/05/31 | Precast U-girder | 93 | — |
| 2019/07/10 | Precast U-girder | 81 | — |
| 2019/10/24 | Precast U-girder | 56 | — |
| 2021/04/07 | Precast U-girder | — | 85 |
| 2021/04/07 | Continuous wall | — | 40 |
| Total | | 230 | 125 |



Rebar Dataset

- **Features and class definitions**
 - Intersection
 - Spacing
- **Labeling configuration**
 - Intersection
 - Def: Overlap area of rebars
 - Shape: Polygon
 - Format: Boundary points
 - Goal: Reference point
 - Spacing
 - Def: Link between intersection
 - Shape: Line
 - Format: Two endpoints
 - Goal: Link prediction



Rebar Dataset

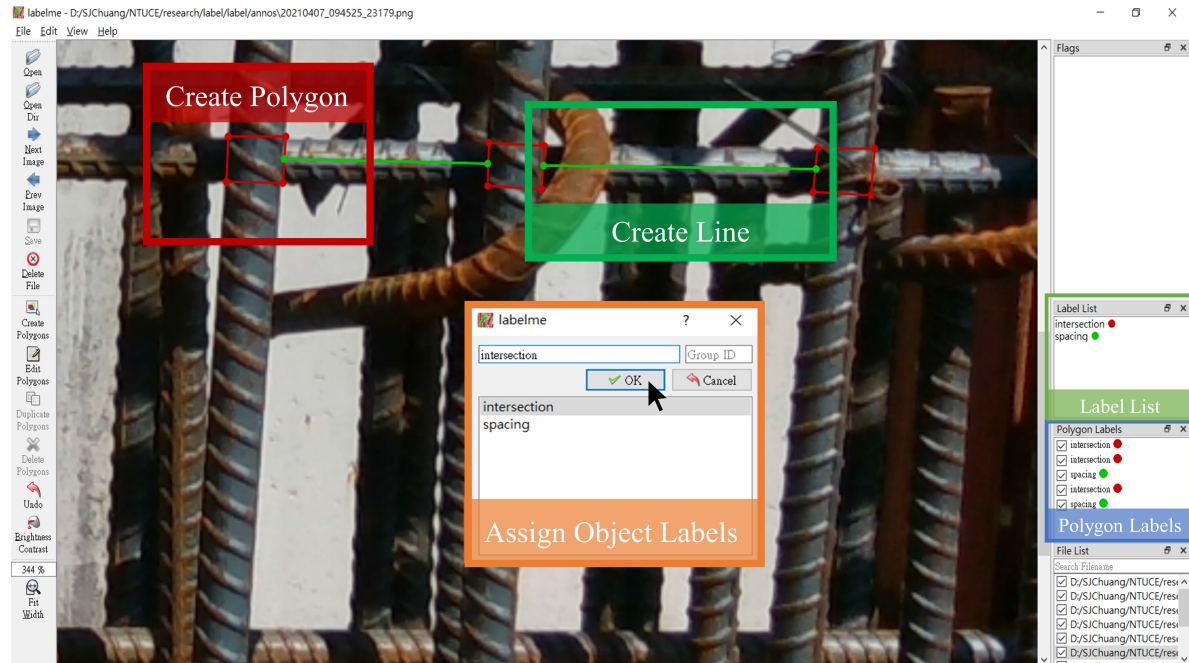
- Labeling tool



labelme

- Saved format (.json)

```
“shapes”: [  
  {  
    “label”: “intersection”,  
    “points”: [  
      [504, 7], [501, 44], [532, 48],  
      [534, 8]  
    ],  
    “shape_type”: “polygon”  
  },  
  {  
    “label”: “spacing”,  
    “points”: [  
      [924, 162], [924, 59]  
    ],  
    “shape_type”: “line”  
  }  
]
```



Deep Learning Models

- **Dataset preparation**

- 230 labeled data from **Precast U-girder in 2019**
- Data splitting: Training [179], validation [22], testing [29]
- Preprocessing: centroid point and line segment to polygon conversion

- **Loss**

- $L = L_{cls} + L_{box} + L_{mask} + \lambda L_{keypoint}$

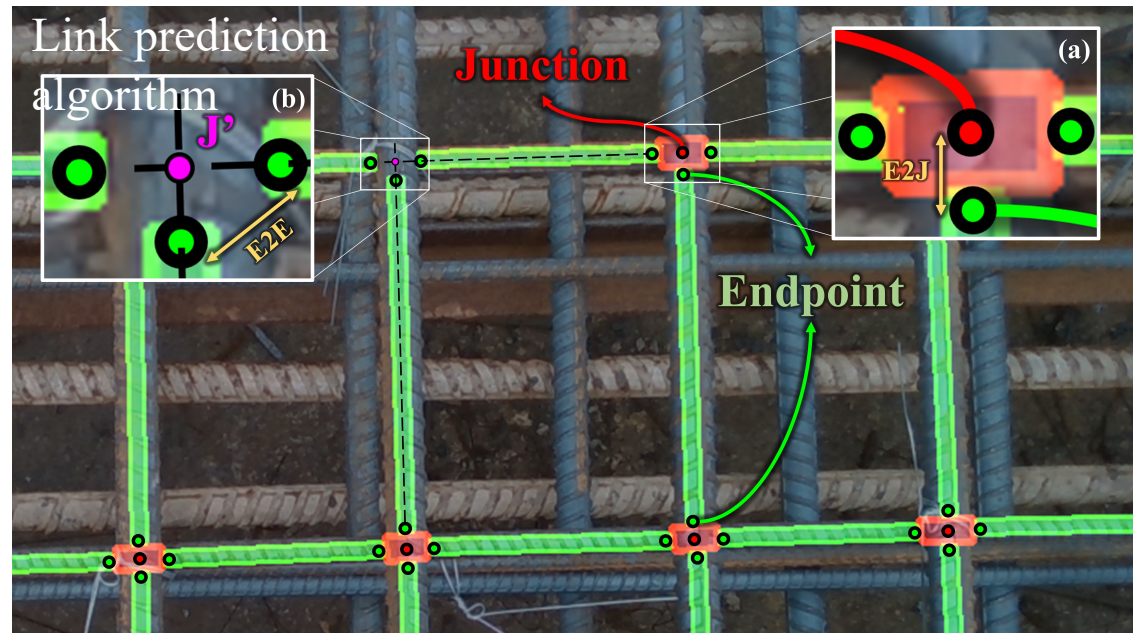
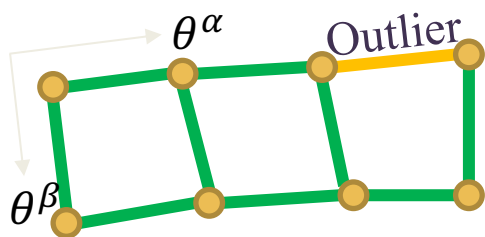
- **Performance metrics**

- Average precision
 - Area under precision-recall curve
 - AP_{50} : AP at IoU = 0.50
 - AP: mean AP at IoU = 0.50 : 0.05 : 0.95
 - AP, AP_{50} , AP_{75}
- Dice coefficient (DC)
 - DC_j : How accurate is the indexed point (*Junction*)
 - DC_L : How accurate are the paired points (*Link*)

| Mask R-CNN config | Description |
|---------------------------|-------------------|
| Framework | Detectron2 (FAIR) |
| Input format | RGB |
| Backbone | ResNet-101-FPN |
| Pretrained weights | MS COCO |
| Batch size | 4 |
| Iteration | 30,000 |
| Optimizer | SGD |
| Base learning rate | 0.0002 |

Post Processing

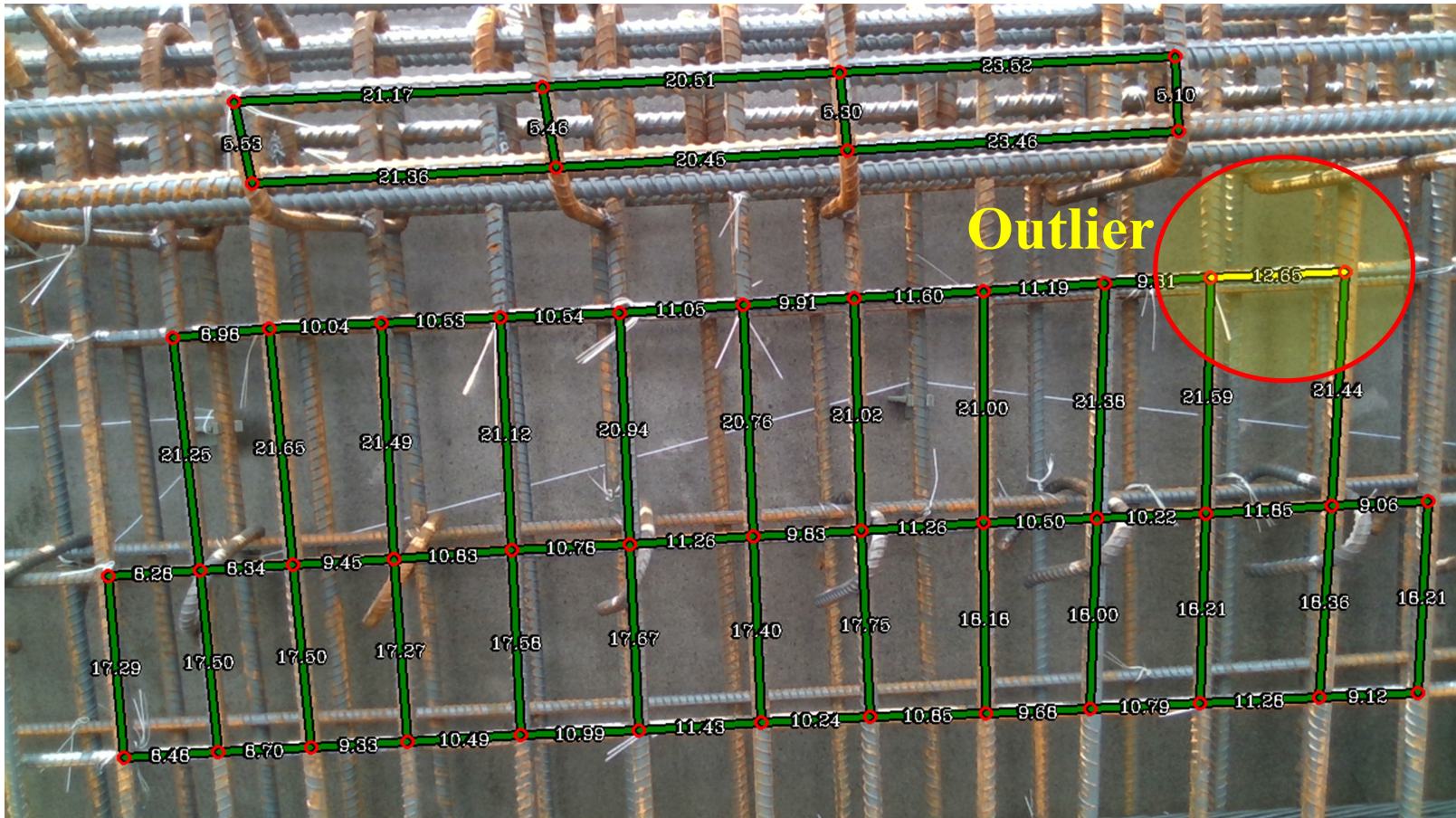
- **Link prediction**
 - $\delta_{E2J} = 30 px$
 - $\delta_{E2E} = 50 px$
- **Spacing measurement**
- **Visualization**
- **Active screening**



Rebar Spacing Measurements



Rebar Spacing Measurements



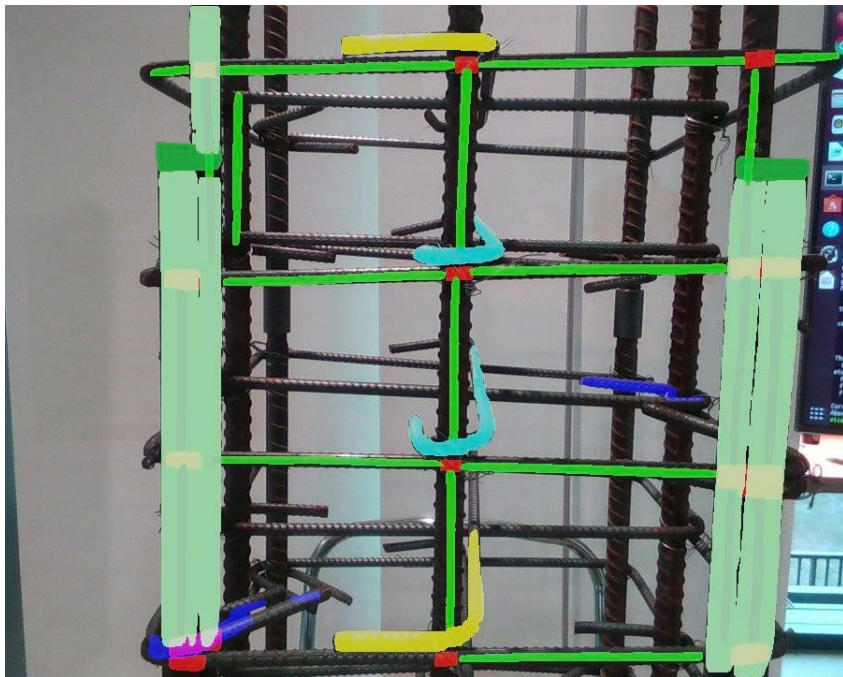
$$\text{Absolute Error (AE)} = |S_{pred} - S_{GT}|$$

$$\text{Relative Error (RE)} = \frac{|S_{pred} - S_{GT}|}{S_{GT}}$$

| Detected spacings | AE (cm) | RE (%) |
|-------------------|---------|--------|
| 1368 | 0.166 | 1.388 |

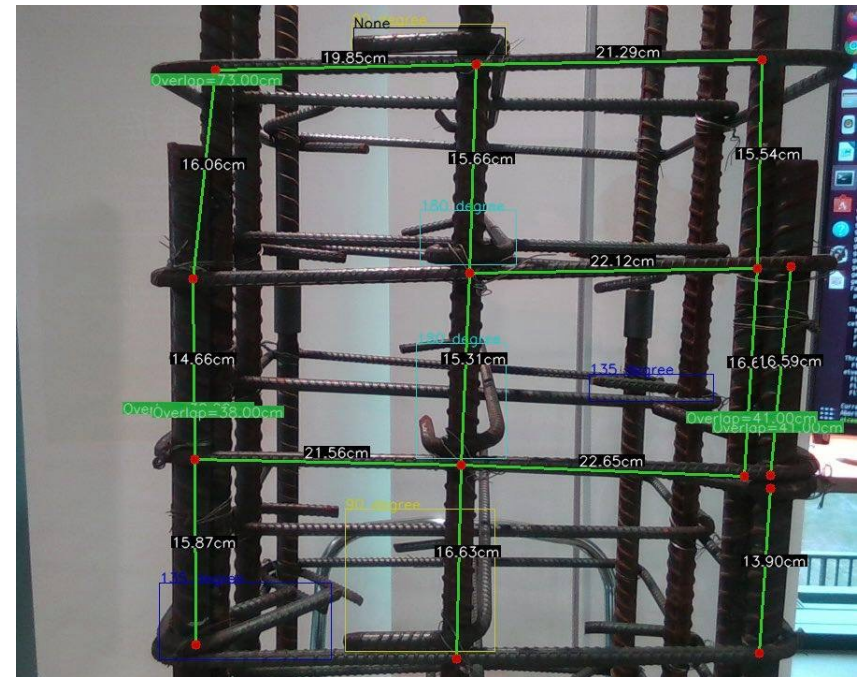
Mask R-CNN + Link Prediction Algorithm

Mask R-CNN 實例分割預測



空間自動量測與物件定位

以演算法獲取實例分割圖中的關鍵像素點或定界框後，索引三維點雲座標，即可計算空間距離，達成自動量測效果。



人工智慧輔助工地鋼筋查驗智慧裝置



立體深度相機

影像串流



觸控式面板

使用者互動



GPU邊緣運算平台
(AI核心計算)

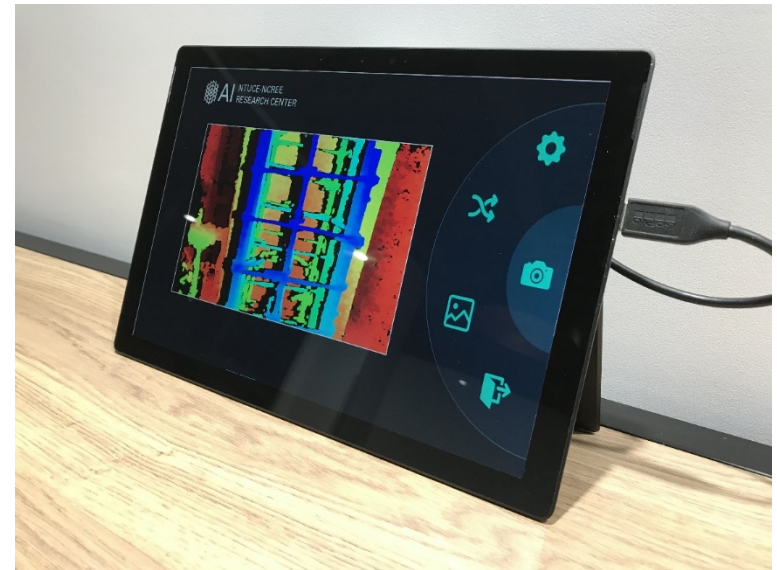
電源模組



供應電源



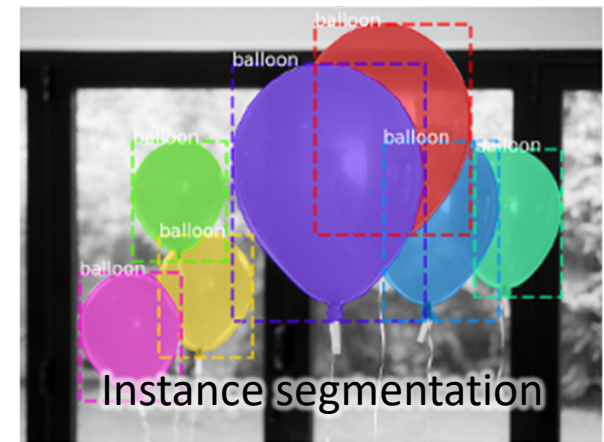
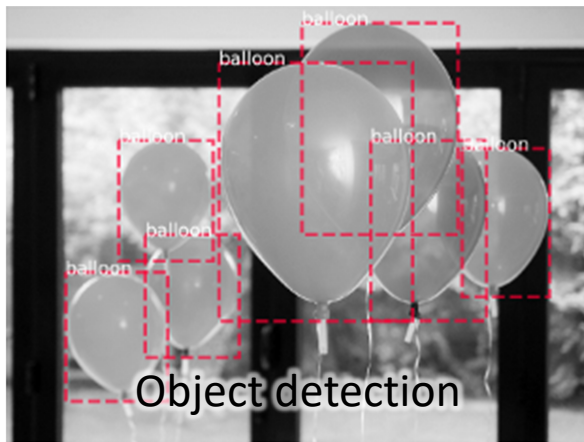
人工智慧輔助工地鋼筋查驗智慧裝置



Rebar Inspection using SSL, Active Learning & Domain Adaptation

Instance Segmentation

- **Levels of image recognition**
 - Object detection (bounding-box level)
 - Semantic segmentation (pixel-level segmentation)
 - Instance segmentation (instance-level segmentation)



- **Labeling issues**
 - Time-consuming & costly
 - Annotation by domain experts

Rebar Dataset

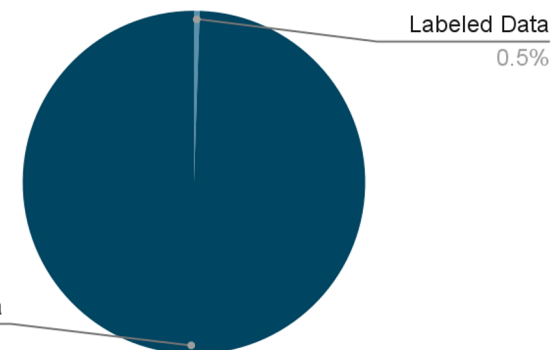


- Labeled data: 50 ~ 200 images per domain
 - Pixel-wise labels
 - Labor-selected samples that should represent the domain data well
 - **But** the trained model only works on old known domain
- Unlabeled data: 8,000 ~ 37,000 images per domain
 - Large amount of continuous & highly similar images per shoot
 - Easy to collect on new domains
 - **But** not usable in supervised learning



What a waste
not using them
in model training!

Rebar Dataset



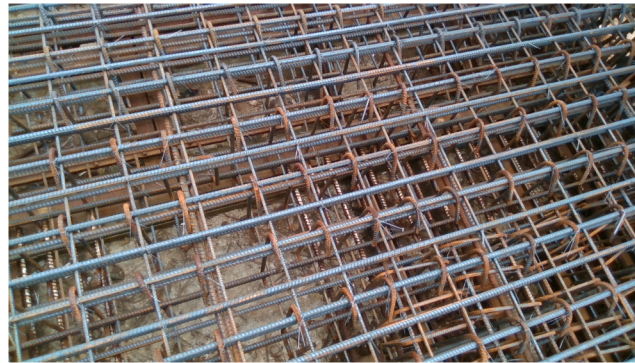
Rebar Dataset

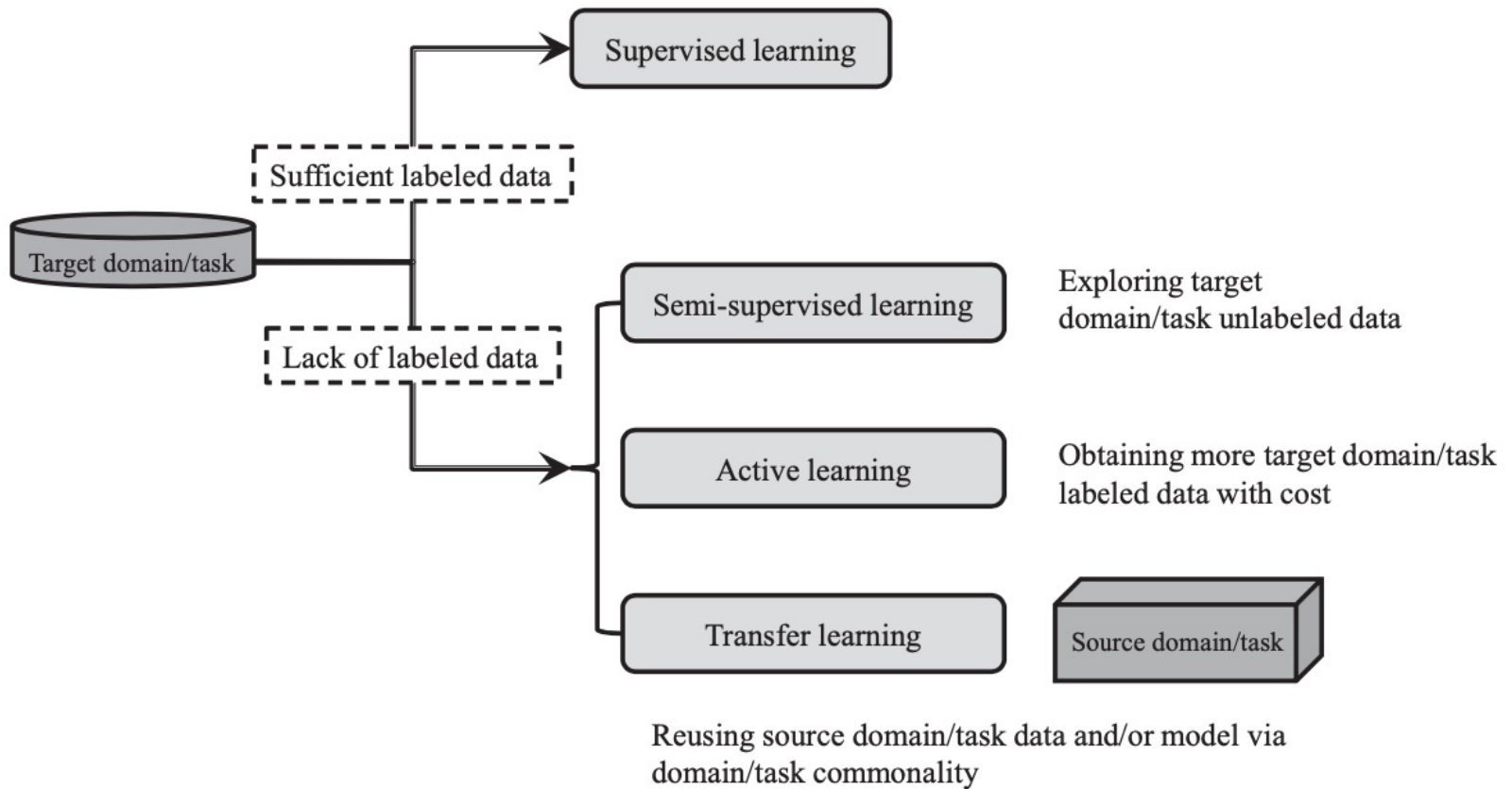
Domain variance:

- rebar assembly
- collecting time
- shooting position



The current deep model by **supervised training** only performs well on its trained domain due to domain variance.





Active Learning

Small data for big performance

Active Learning

- **Definition**

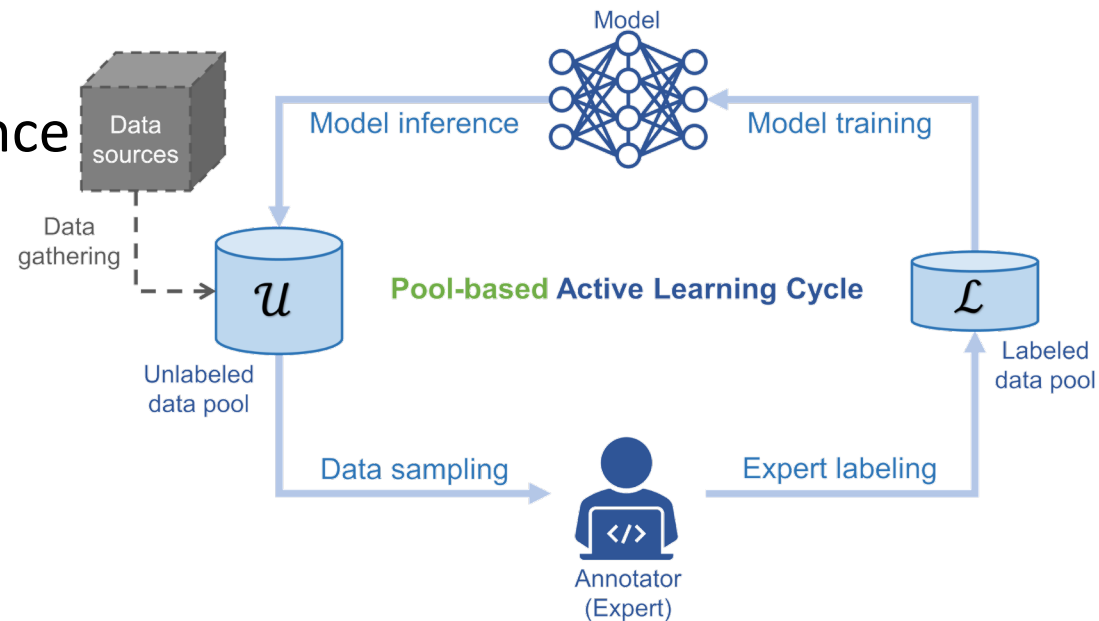
- A Subfield of machine learning.
- A learning algorithm interactively query oracle to label new data with expected output.
- Query learning, optimal experimental design.

- **Uncertainty sampling**

- Query strategy
- Least model confidence

- **Pool-based active learning cycle**

- **Data sampling**
- Expert labeling
- Model training
- Model inference



Active Learning

- Active learning loop
- Active learning for object detection
 - Entropy-based uncertainty measurement
 - Aggregation function (Sum, Average, Max)
 - Ensemble-based disagreement measurement
 - Consensus score
 - RoI matching
- Active learning with clustering

Algorithm 1 Active learning loop

\mathcal{U} : A set of unlabeled data $\{x^1, x^2, x^3, \dots\}$

\mathcal{L} : A set of labeled data $\{\langle x^a, y^a \rangle, \langle x^b, y^b \rangle, \langle x^c, y^c \rangle, \dots\}$

B : Labeling budget

for i in B **do**

 Train a model \mathcal{M} based on \mathcal{L}

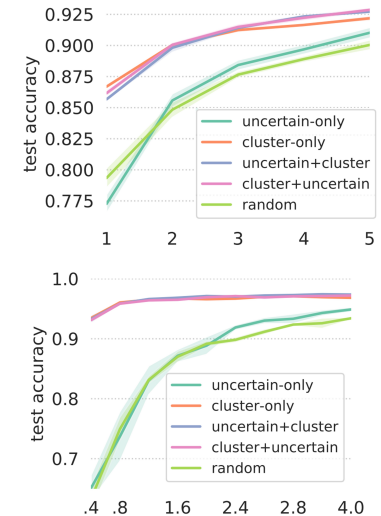
Select the most uncertain instance $x^* \in \mathcal{U}$ according to \mathcal{M}

 Query the oracle to obtain label y^*

 Let $\mathcal{L} \leftarrow \mathcal{L} \cup \{x^*, y^*\}$

 Let $\mathcal{U} \leftarrow \mathcal{U} \setminus \{x^*\}$

end for



IoU = 0.85

Consensus score = $1 - 0.85$



IoU = 0.85, $\mathcal{VR} = 1 - 2/3$

Consensus score $\mathcal{VR} = 1 - 0.561$

Active Learning Algorithms

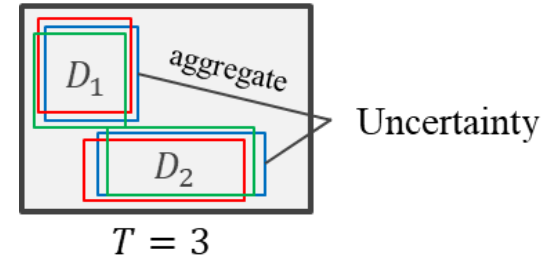
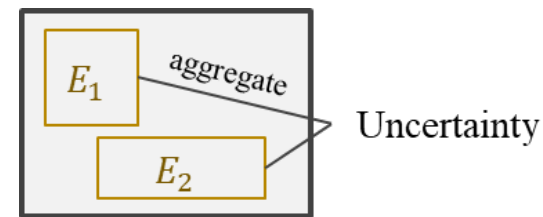
- **Uncertainty estimation**

- Entropy of the probability distribution

- **Three aggregation functions** (\sum , $\frac{1}{N}\sum$, \max_E)

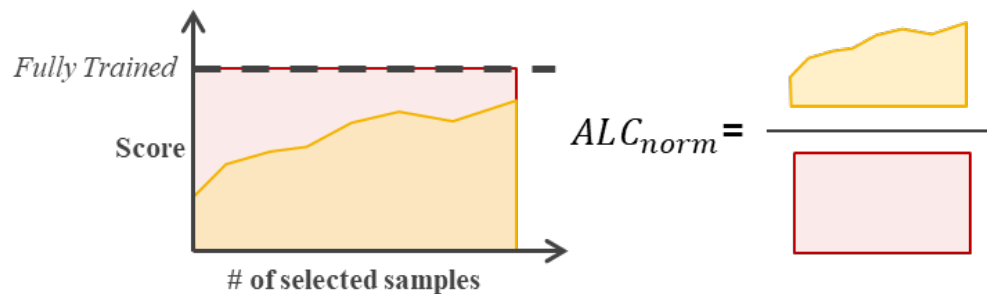
- **RoI matching method**

- Generate controversial predictions through **MC dropout**
- **Three disagreement measures** (E_{vote} , $E_{consensus}$, Div_{KL})
- Aggregated by average

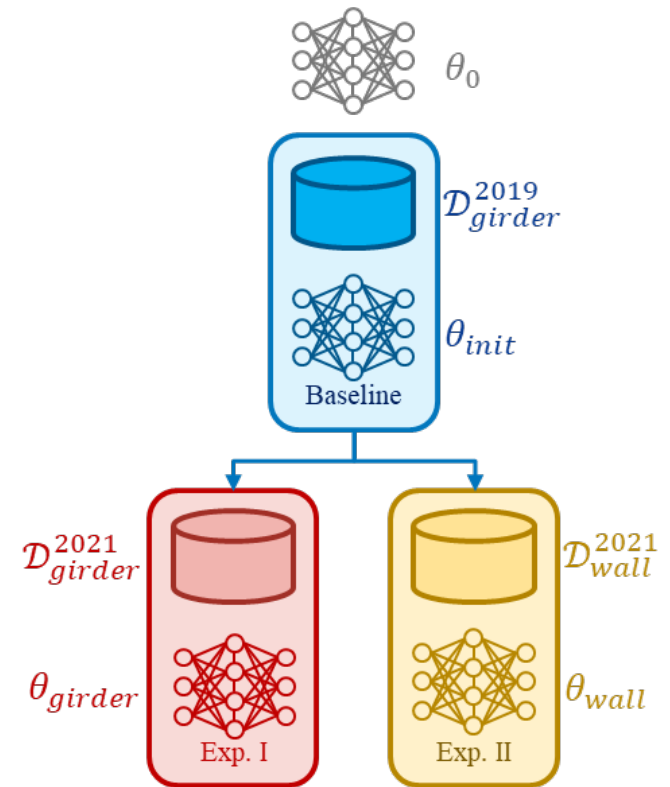
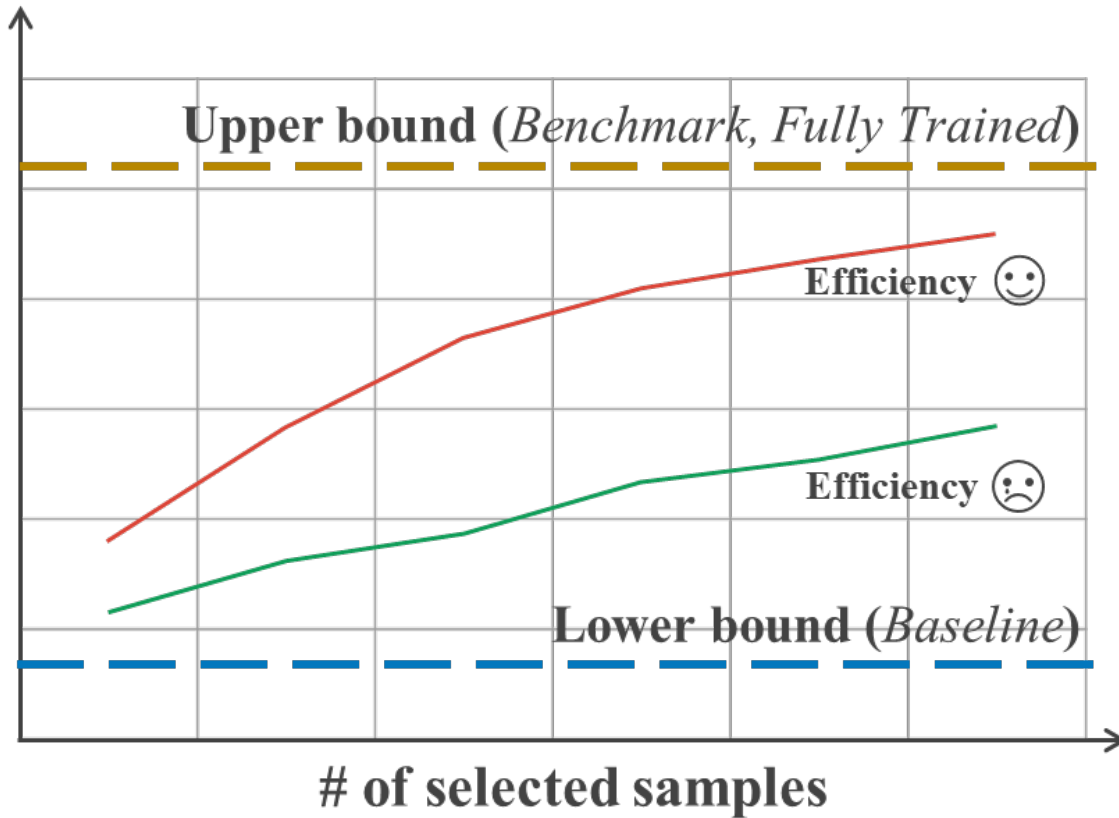


- **Performance metrics**

- Normalized area under the learning curve ALC_{norm}



Active Learning Experiments

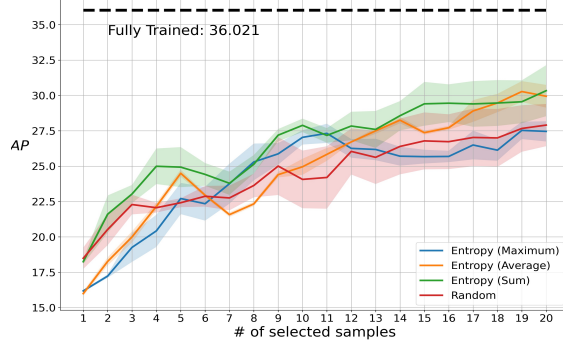


Active Learning Experiments (Entropy)

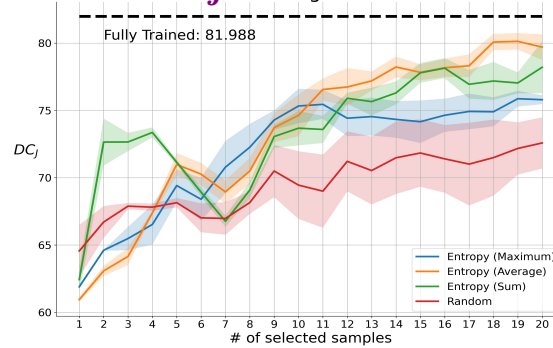
Sum, Average, Maximum, Random

Exp. I

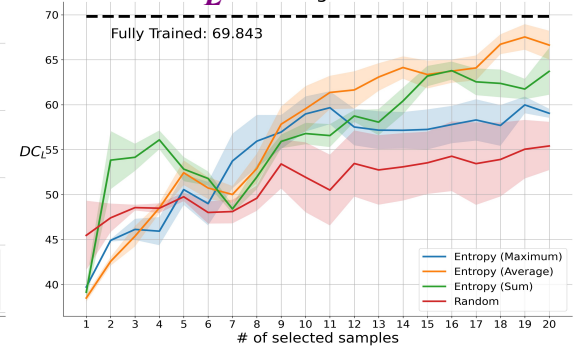
AP Learning Curve



DC_J Learning Curve

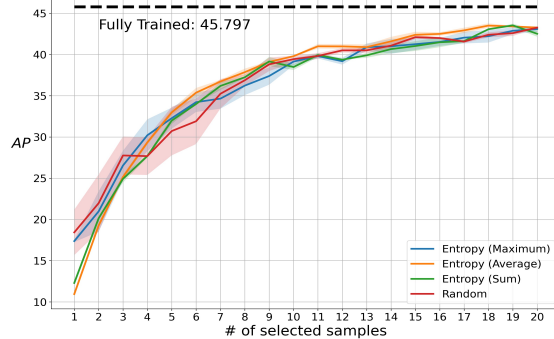


DC_L Learning Curve

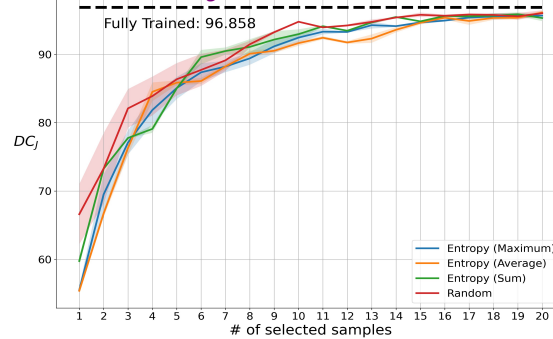


Exp. II

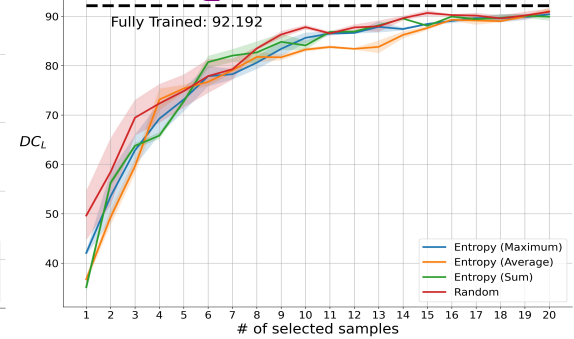
AP Learning Curve



DC_J Learning Curve



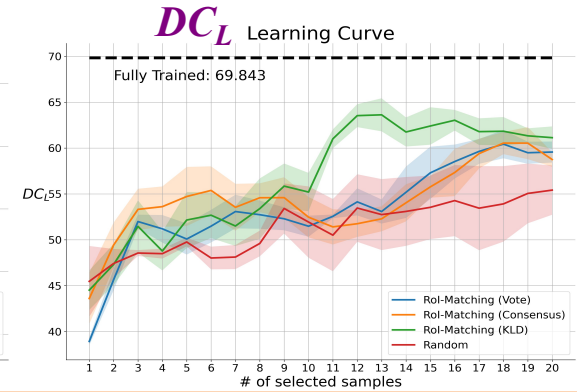
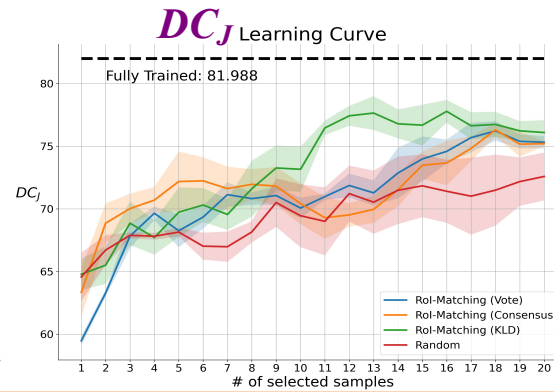
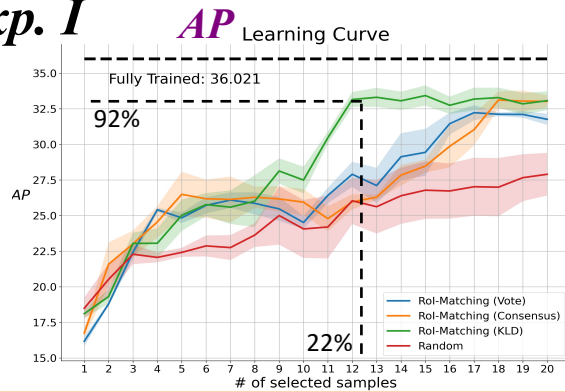
DC_L Learning Curve



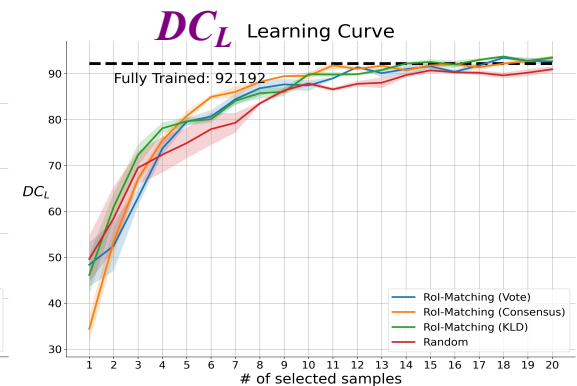
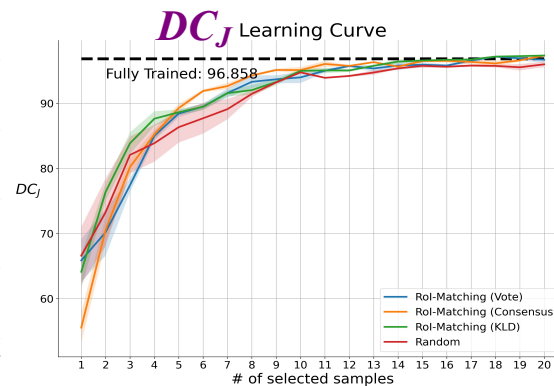
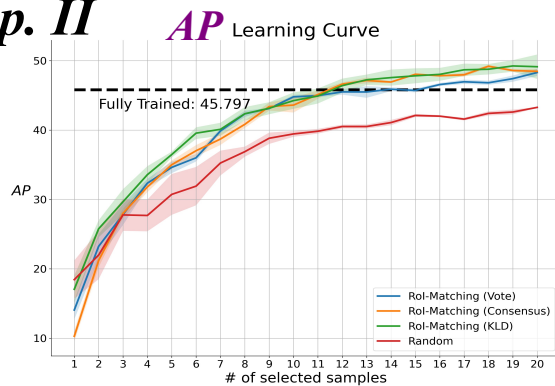
Active Learning Experiments (RoI Matching)

KL Divergence, Consensus Entropy, Vote Entropy, Random

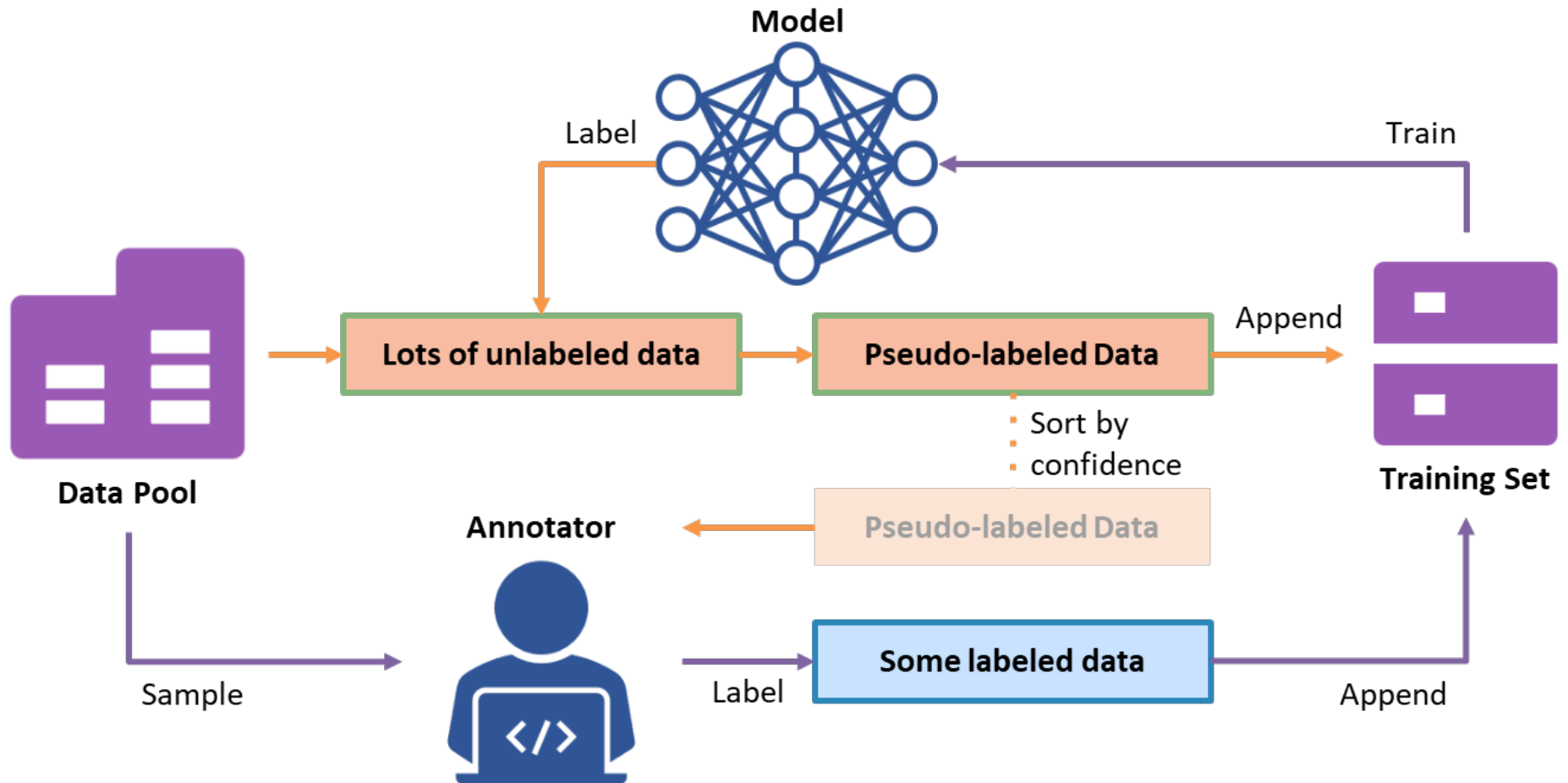
Exp. I



Exp. II



Active Learning + Pseudo Labeling

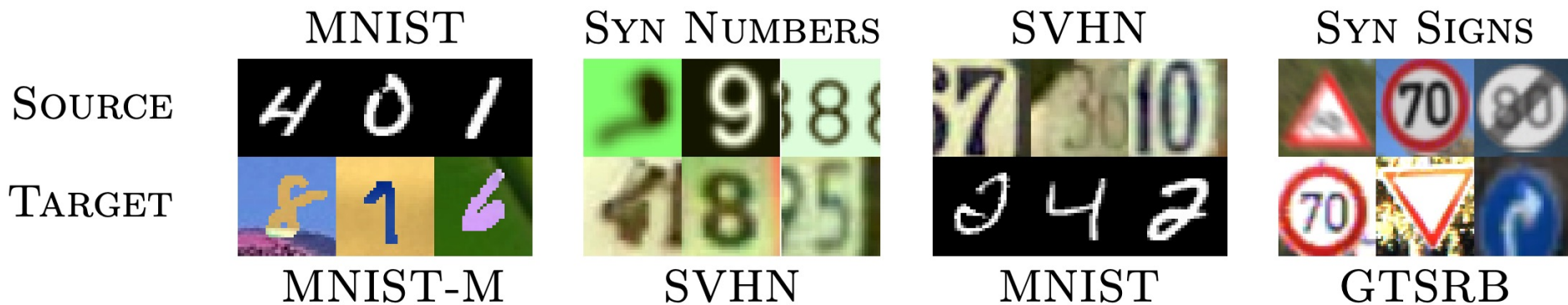


Domain Adaptation

TL will be the next driver of ML commercial success after supervised learning,
Andrew Ng (2016 NIPS)

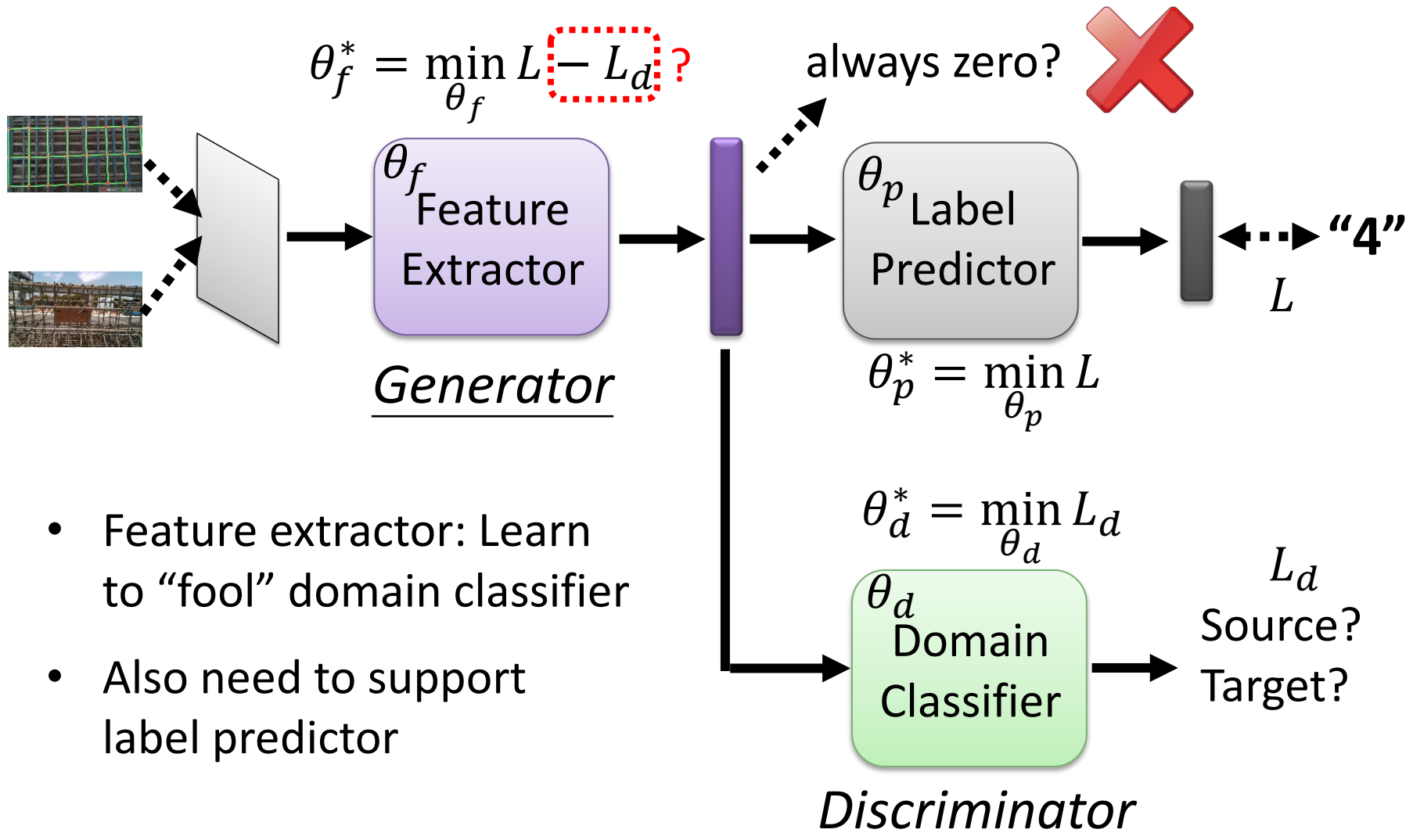
Domain Adaptation: A Subfield of Transfer Learning

Domain adaptation is a specific scenario where the label space remains same, yet the probabilities between source and target domains change $P(X_s) \neq P(X_t)$



Domain Adversarial Training

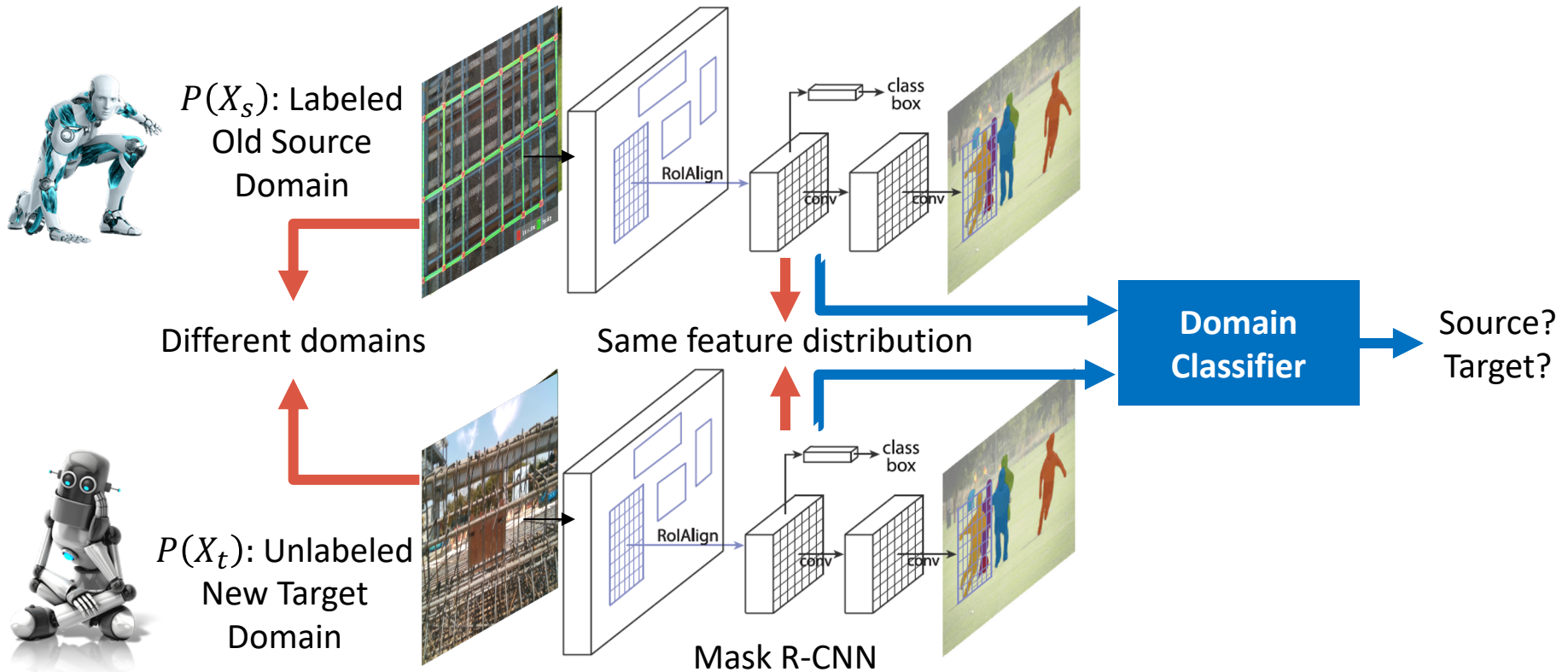
credit: Hung-Yi Lee,
<https://speech.ee.ntu.edu.tw/~hylee/ml/2021-spring.html>



- Feature extractor: Learn to “fool” domain classifier
- Also need to support label predictor

Domain Adaptation for Rebar Image Segmentation

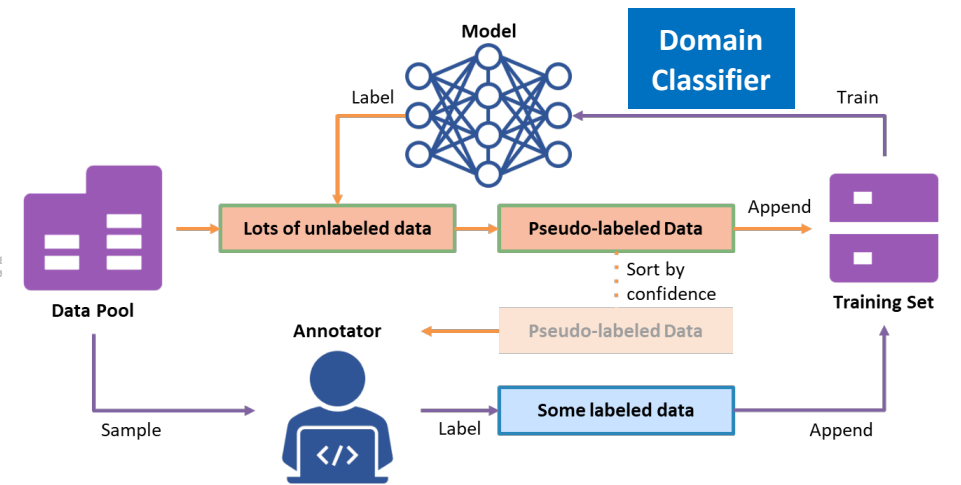
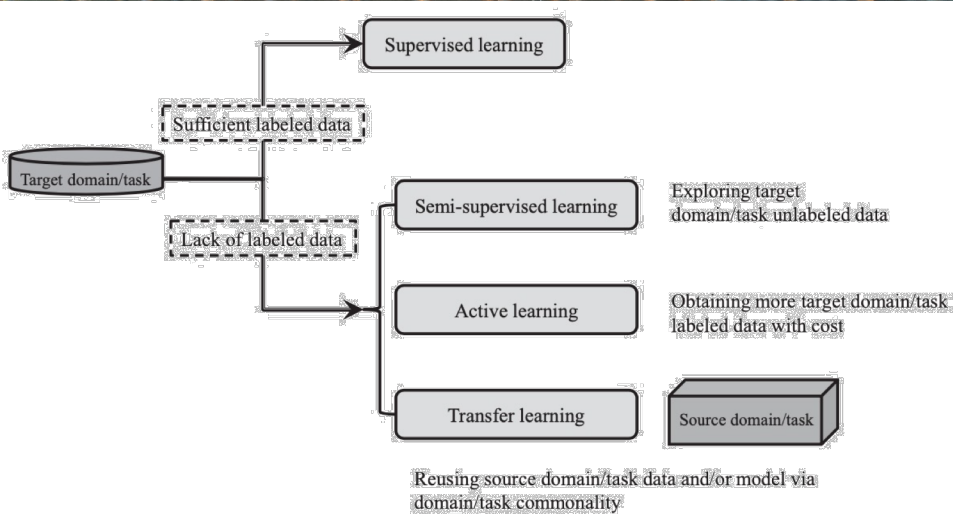
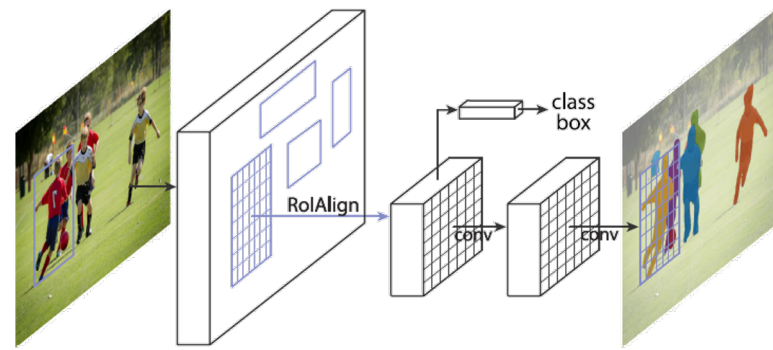
- **Domain variance** in rebar dataset:
rebar assembly, collecting time, shooting position
- **Domain adversarial training:** reduce discrepancy between domains
 - **Domain classifier:** try to distinguish between source and target domain
 - **Feature extractor:** try to fool domain classifier while training model





labelme

Summary



Yang et al., Transfer Learning, Cambridge University Press, 2020.

Digital Twin