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#073374](https://www.sli.do/#073374)



## Deep Learning for Computer Vision (III)

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### Learning Objectives

- Learn the basic concepts of transfer learning.
- Learn how to use a pretrained network to significantly increase the accuracy of image classification task.

# Improve Performance of Your CNN Model

- Network architecture
  - Number of hidden layers (network depth)
  - Number of neurons in each layer (layer width)
  - Activation type
- Learning and optimization
  - Learning rate and decay schedule
  - Mini-batch size
  - Optimization algorithms
  - Number of training iterations or epochs (and early stopping criteria)
- Regularization techniques to avoid overfitting
  - L2 regularization
  - Dropout layers
  - Data augmentation
- Batch normalization
- Transfer learning

# Transfer Learning

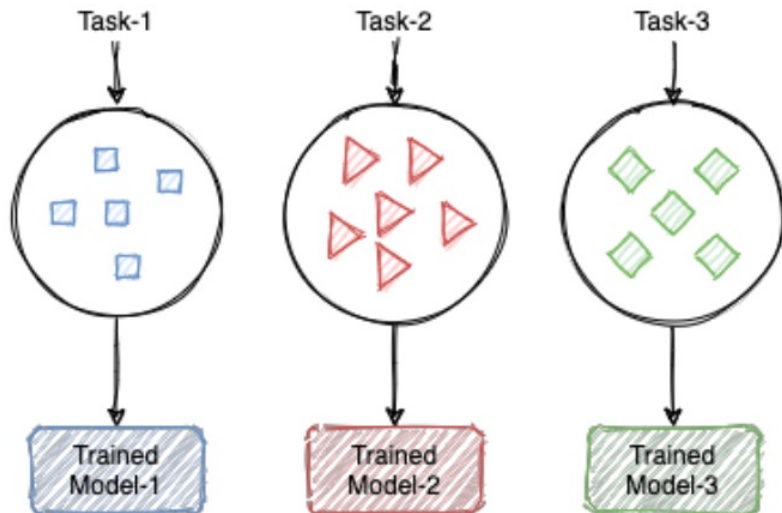
TL will be the next driver of ML commercial success after supervised learning,  
Andrew Ng (2016 NIPS)

# Transfer Learning

- Transfer learning is one of the most important techniques of deep learning.
- Loosely, transfer learning is referred to a situation where what has been learned in one setting is exploited to improve generalization in another setting.

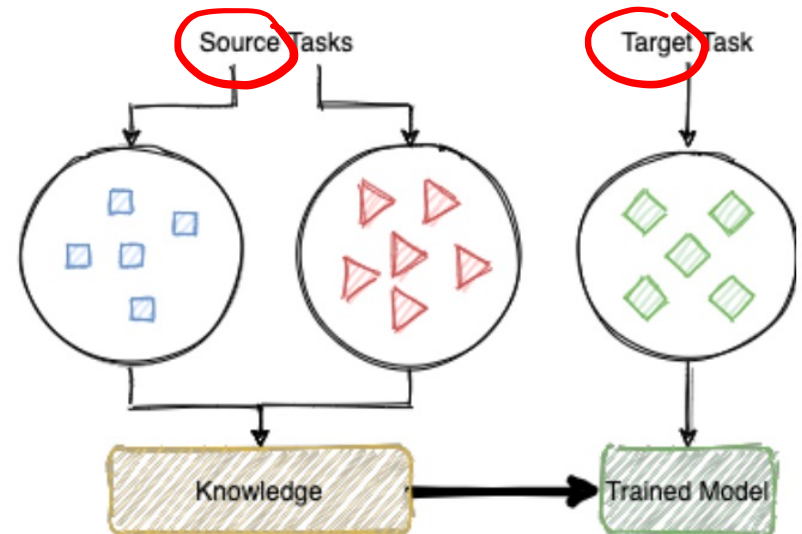
## Traditional Approach

(without Transfer Learning)  
We train for each task in isolation

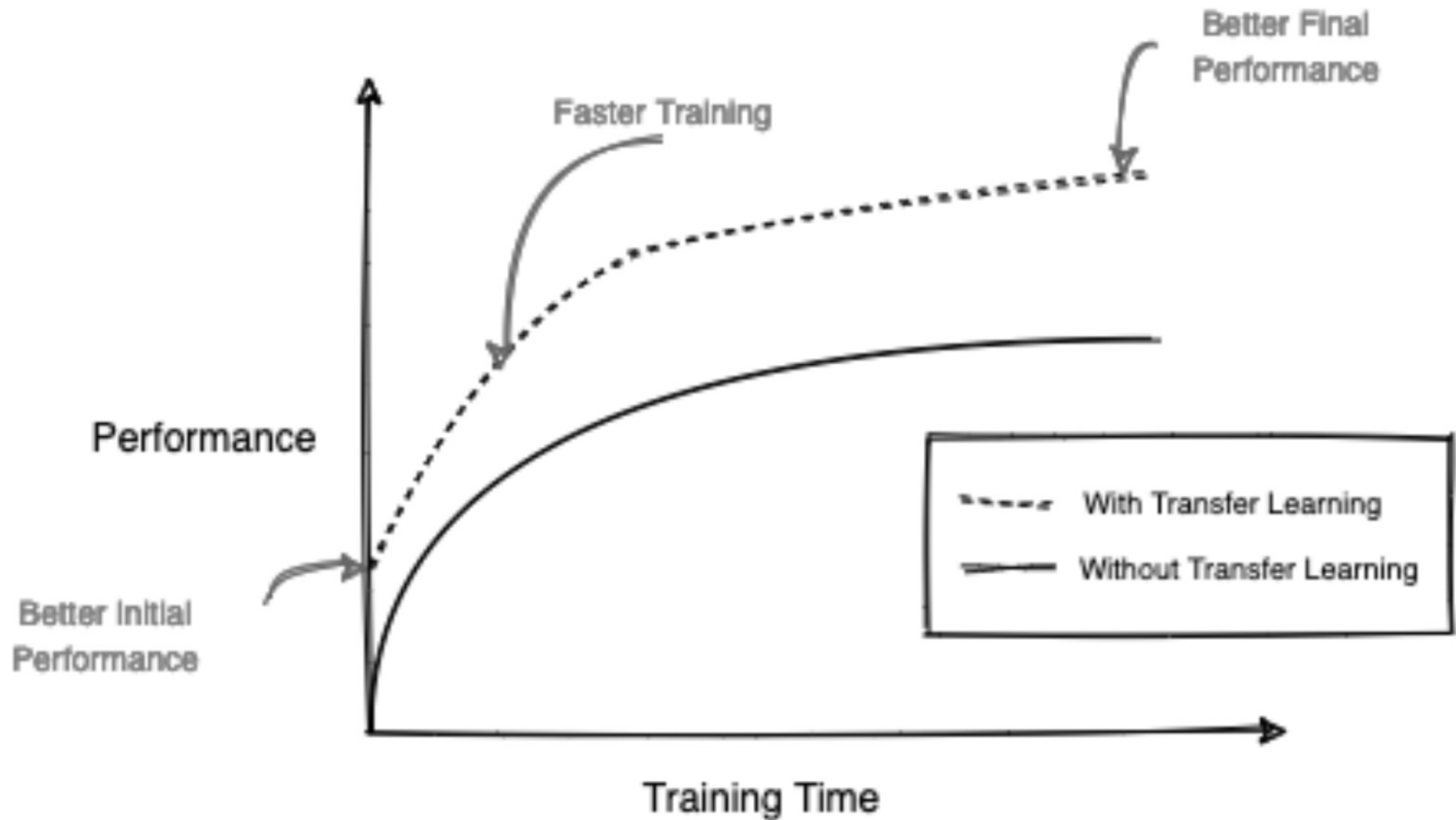


## Transfer Learning

We leverage knowledge from existing tasks



# Typical Benefit of Transfer Learning



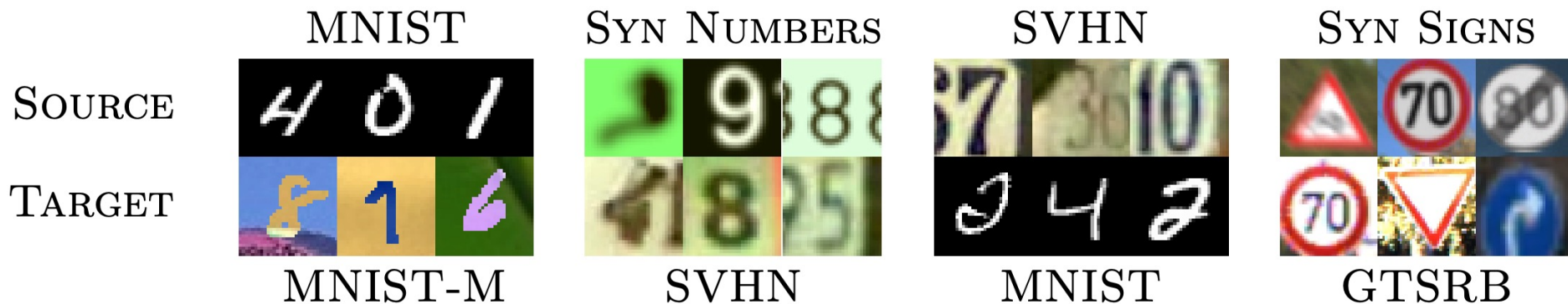
# Transfer Learning: A Formal Definition

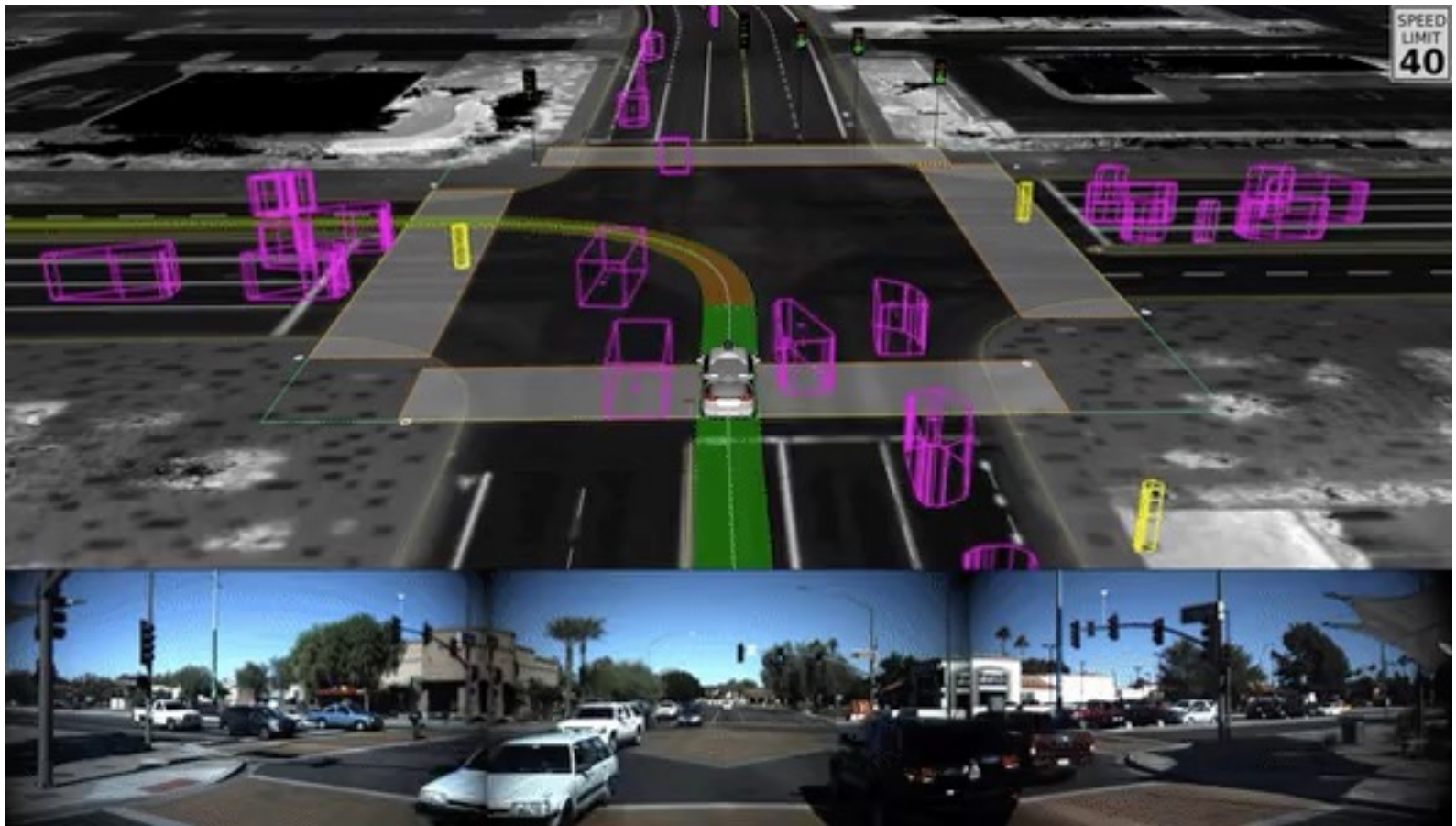
- The definition of transfer learning is given in terms of domains and tasks.
- A domain  $\mathbb{D}$  consists of a feature space  $\mathcal{X}$  and a probability distribution  $P(X)$  where  $X = \{x_1, x_2, \dots, x_n\} \in \mathcal{X}$
- A task  $\mathbb{T}$  consists of a label space  $\mathcal{Y}$  and a predictive function  $f: \mathcal{X} \rightarrow \mathcal{Y}$

Given a source domain  $\mathbb{D}_s$  and a learning task  $\mathbb{T}_s$ , a target domain  $\mathbb{D}_t$  and a learning task  $\mathbb{T}_t$ , transfer learning aims to help improve the learning of the target predictive function  $f_t(\cdot)$  for the target domain using the knowledge in  $\mathbb{D}_s$  and  $\mathbb{T}_s$ , where  $\mathbb{D}_s \neq \mathbb{D}_t$  or  $\mathbb{T}_s \neq \mathbb{T}_t$

# Domain Adaptation: A Subfield of Transfer Learning

Domain adaptation is a specific scenario where the label space remains same, yet the probabilities between source and target domains change  $P(X_s) \neq P(X_t)$





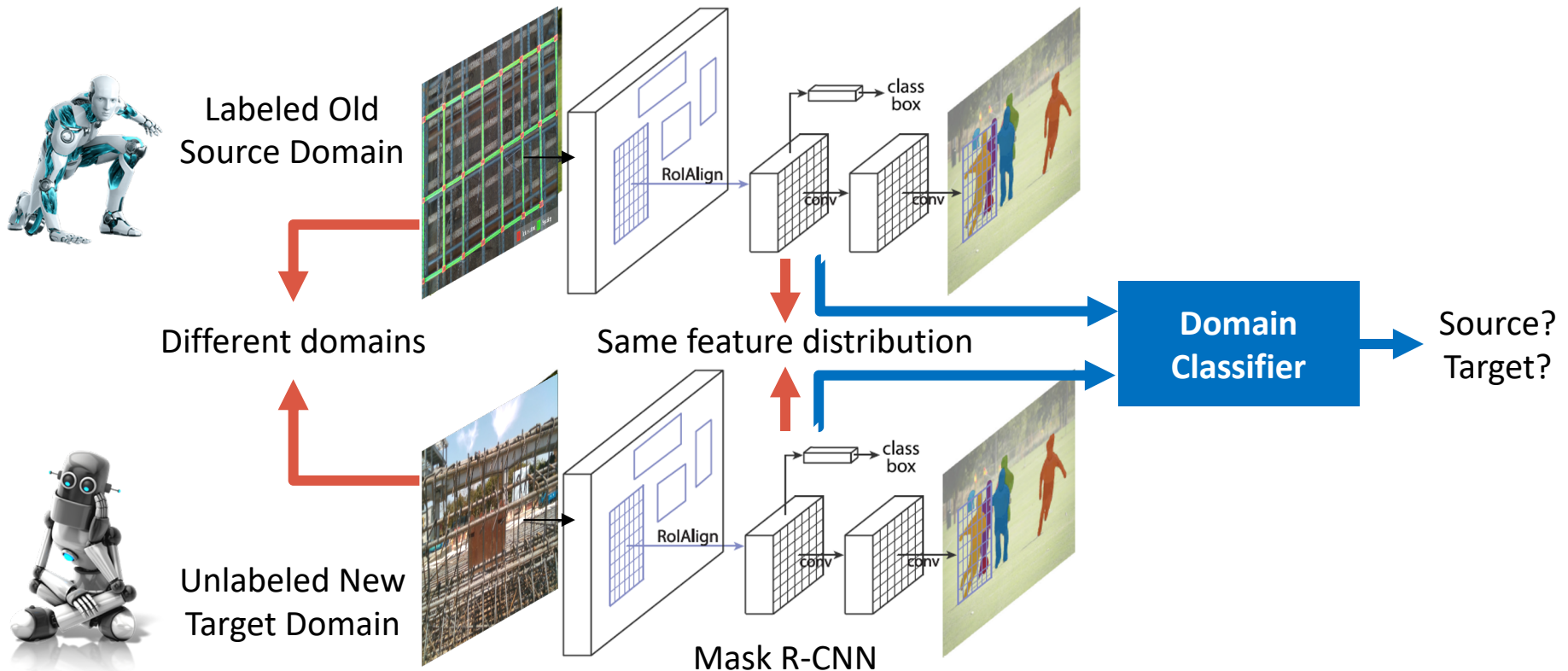
## Waymo's Cars Drive 10 Million Miles (A Day in Virtual Space, 10 Years in Real Space)

<http://dipakramoliya.com/uncategorized/in-a-perilous-virtual-world-waymos-cars-drive-10-million-miles-a-day/>



# Domain Adaptation for Rebar Image Segmentation

- **Domain variance** in rebar dataset:  
rebar assembly, collecting time, shooting position
- **Domain adversarial training:** reduce discrepancy between domains
  - **Domain classifier:** try to distinguish between source and target domain
  - **Feature extractor:** try to fool domain classifier while training model

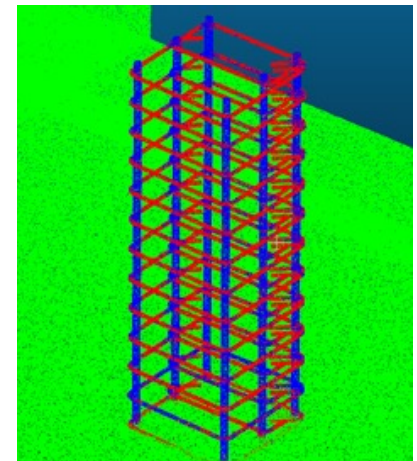
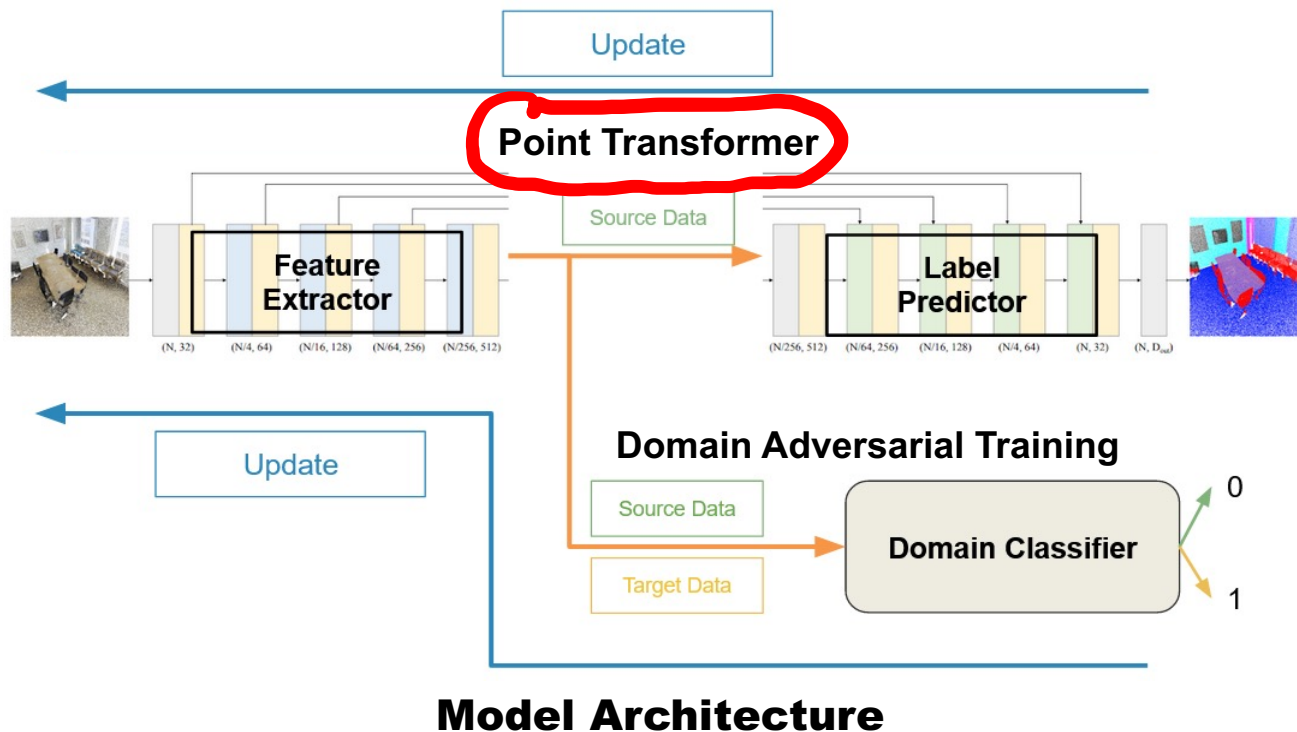


# Domain Adaptation for Rebar Point Cloud Segmentation

Task: 3D semantic segmentation

Classes:

1. Background
2. Main rebars (主筋)
3. Ties (箍筋)



## Source Data

- Virtual (parametric modeling by Revit)
- Labeled (automatic)



## Target Data

- Real (SfM + MVS)
- Unlabeled

# Transfer Learning for Image Classification

# Transfer Learning for Image Classification: Rationale

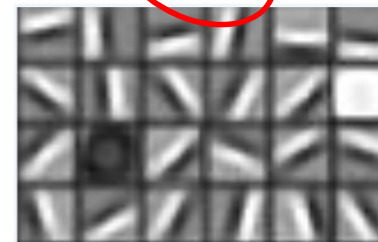
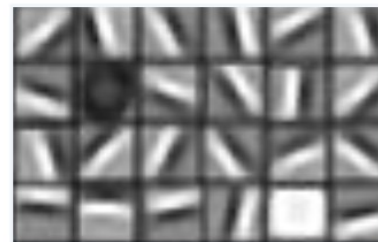
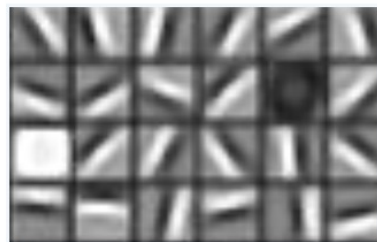
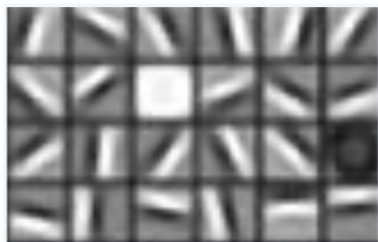
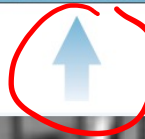
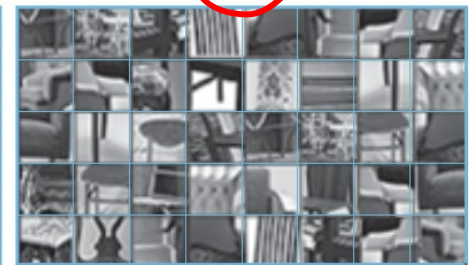
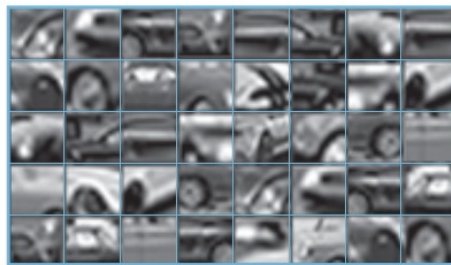
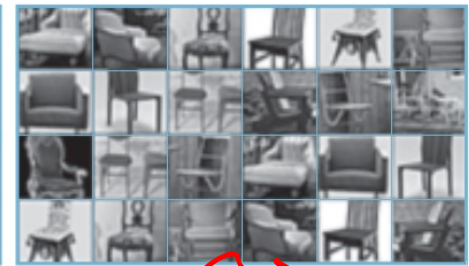
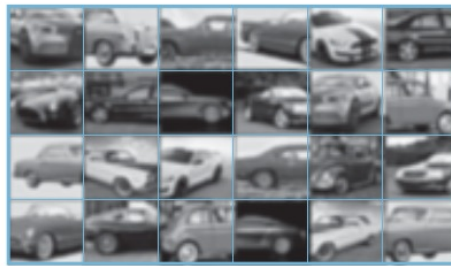
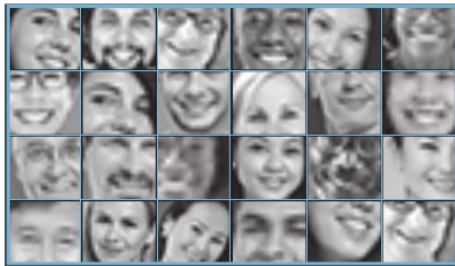
- A CNN learns the features in a dataset step by step in increasing levels of complexity. These are called feature maps. The deeper you go through the network layers, the more image-specific features are learned.

Faces

Cars

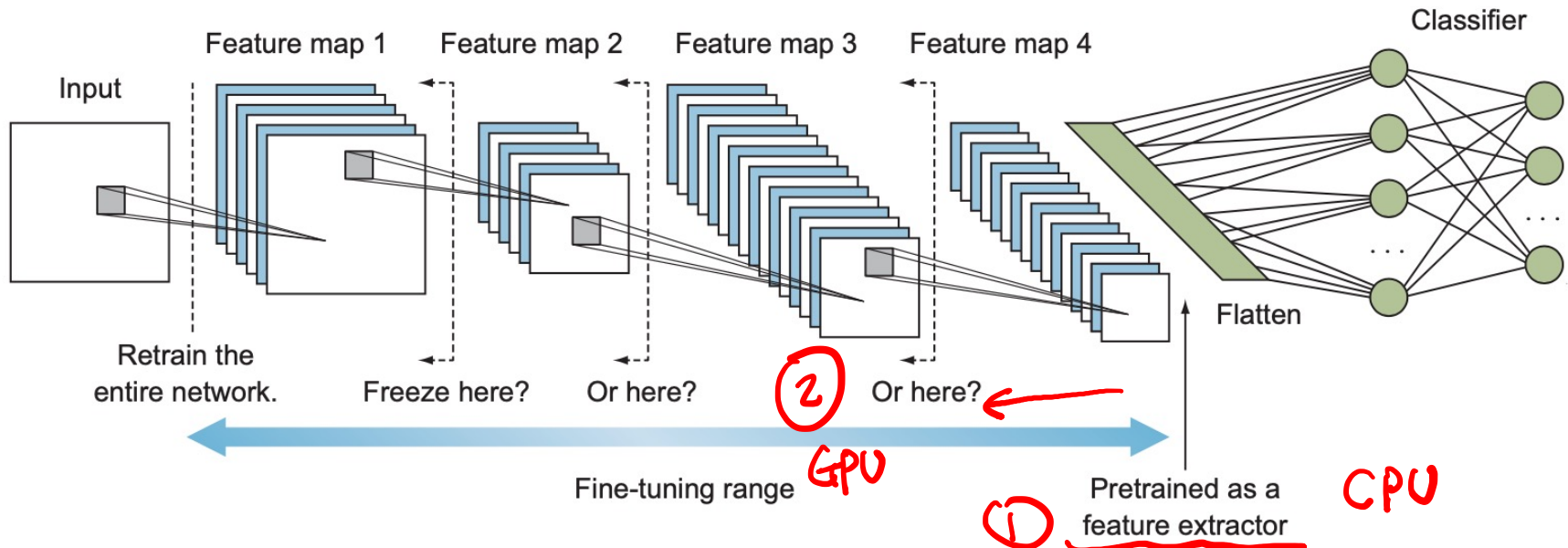
Elephants

Chairs



# Transfer Learning for Image Classification: How

- Instead of starting from scratch, we can leverage a pretrained neural network (often a complex NN such as ResNet) and use their optimized parameters (weights) trained on a large dataset as a starting point to train our model on a smaller dataset for a given task.
- See CNN\_Transfer\_Learning\_Part1.pdf





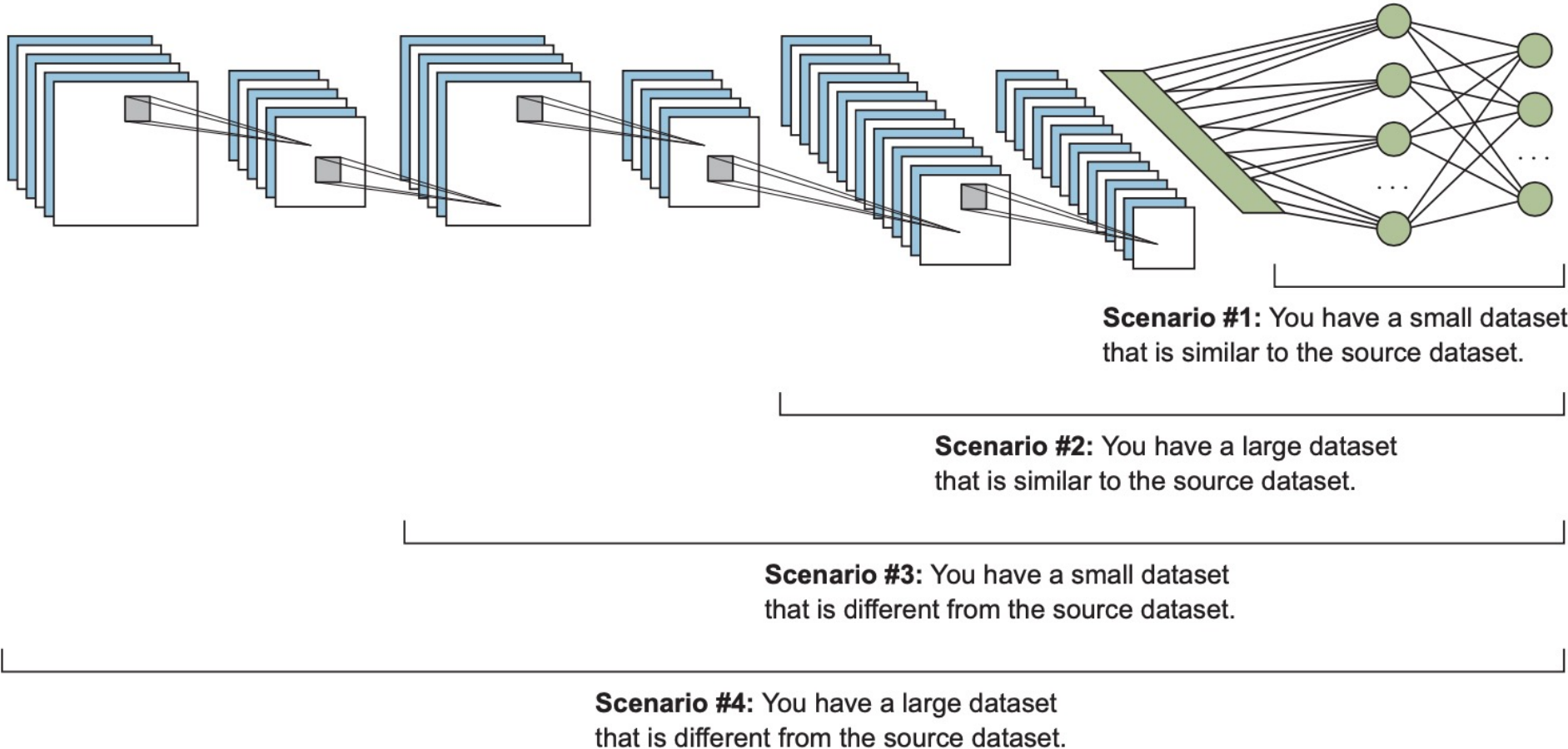
# Transfer Learning Scenarios

*source*

Scenario	Size of the <u>target data</u>	Similarity of the original and new datasets	Approach
①	<u>Small</u>	<u>Similar</u>	Pretrained network as <u>a feature extractor</u>
2	Large ←	Similar	Fine-tune through the full network
③ ↙	<u>Small</u>	<u>Very different</u>	Fine-tune from activations earlier in the network
4	Large ←	Very different	Fine-tune through the entire network

- Scenario 3: see CNN\_Transfer\_Learning\_Part2.pdf

# Summary: Transfer Learning Scenarios and Strategies



## Summary: Transfer Learning

- Given a source domain  $\mathbb{D}_s$  and a learning task  $\mathbb{T}_s$ , a target domain  $\mathbb{D}_t$  and a learning task  $\mathbb{T}_t$ , transfer learning aims to help improve the learning of the target predictive function  $f_t(\cdot)$  for the target domain using the knowledge in  $\mathbb{D}_s$  and  $\mathbb{T}_s$ , where  $\mathbb{D}_s \neq \mathbb{D}_t$  or  $\mathbb{T}_s \neq \mathbb{T}_t$
- Domain adaptation is a subfield of transfer learning where the label space remains same, yet the probabilities between source and target domains change  $P(X_s) \neq P(X_t)$
- Transfer learning migrates the knowledge learned from the source dataset to the target dataset, to save training time and computational cost and to improve generalization in target.
- The two main transfer learning approaches for image classification are using a pretrained network as a feature extractor, and fine-tuning.



# Relationship of transfer learning to other learning paradigms

