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#073374](https://www.sli.do/#073374)



Deep Learning for Computer Vision (III)

Learning Objectives

- Learn the basic concepts of transfer learning.
- Learn how to use a pretrained network to significantly increase the accuracy of image classification task.

Improve Performance of Your CNN Model

- Network architecture
 - Number of hidden layers (network depth)
 - Number of neurons in each layer (layer width)
 - Activation type
- Learning and optimization
 - Learning rate and decay schedule
 - Mini-batch size
 - Optimization algorithms
 - Number of training iterations or epochs (and early stopping criteria)
- Regularization techniques to avoid overfitting
 - L2 regularization
 - Dropout layers
 - Data augmentation
- Batch normalization
- Transfer learning

Transfer Learning

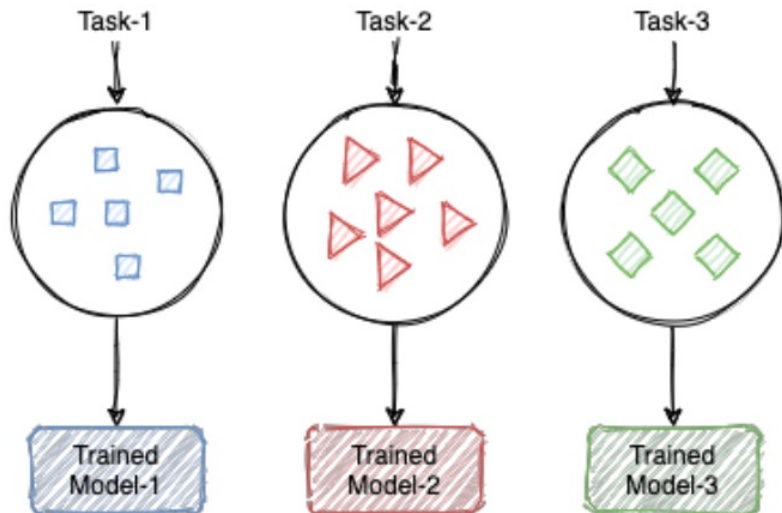
TL will be the next driver of ML commercial success after supervised learning,
Andrew Ng (2016 NIPS)

Transfer Learning

- Transfer learning is one of the most important techniques of deep learning.
- Loosely, transfer learning is referred to a situation where what has been learned in one setting is exploited to improve generalization in another setting.

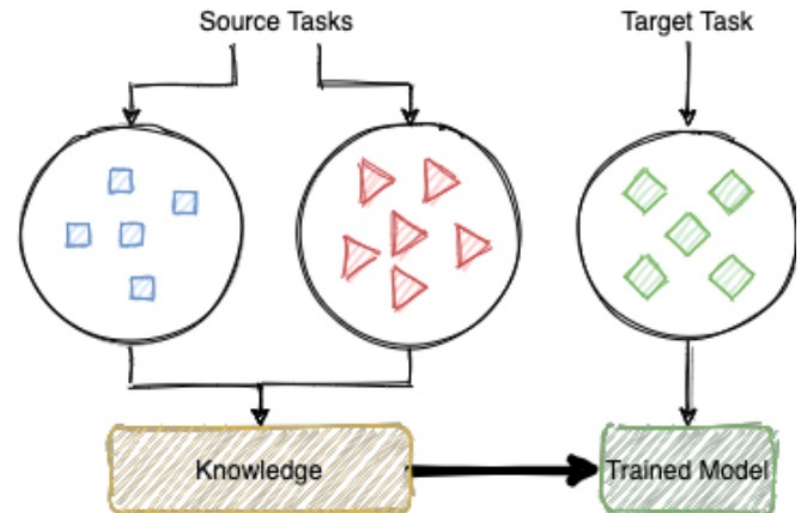
Traditional Approach

(without Transfer Learning)
We train for each task in isolation

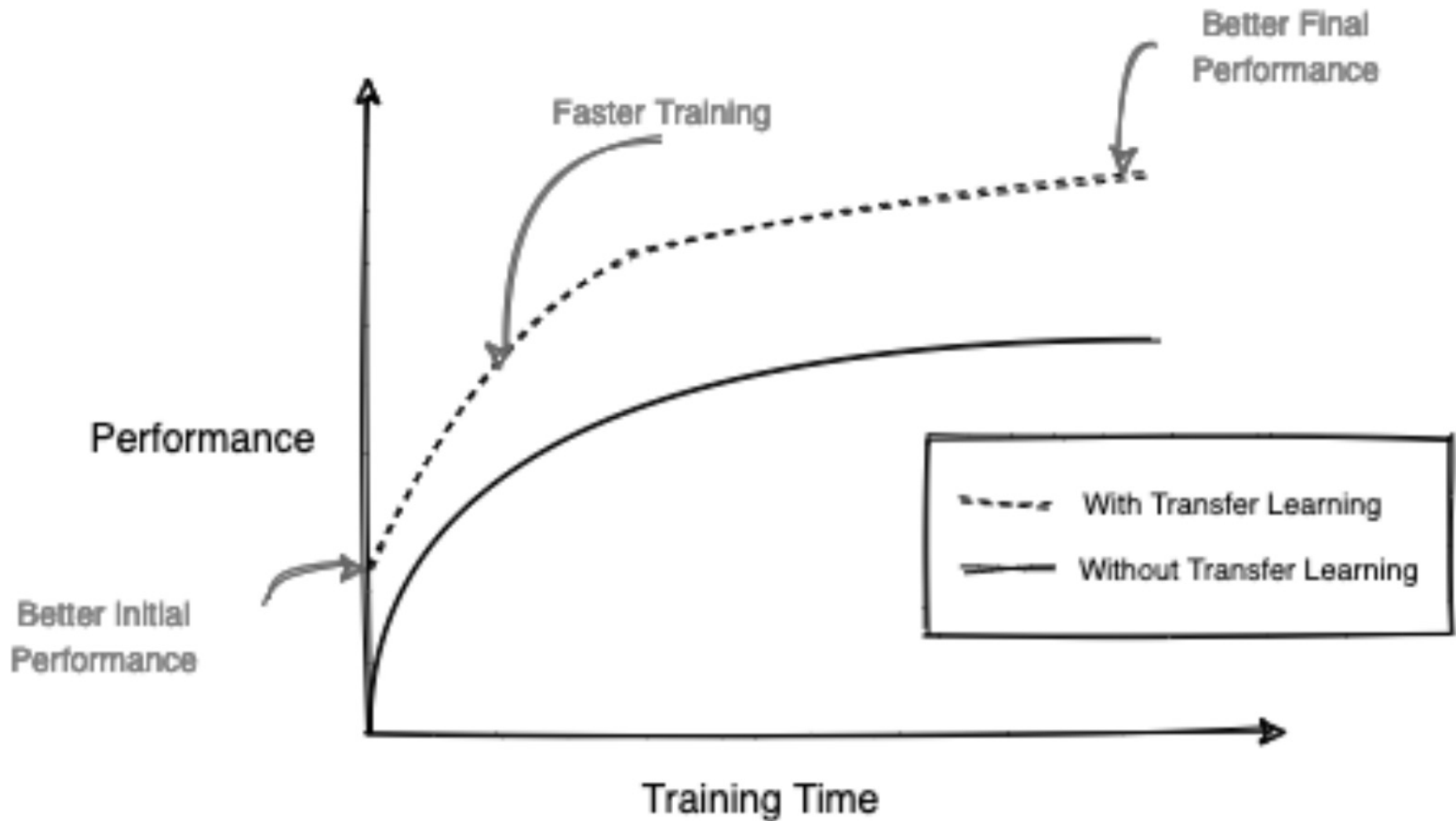


Transfer Learning

We leverage knowledge from existing tasks



Typical Benefit of Transfer Learning



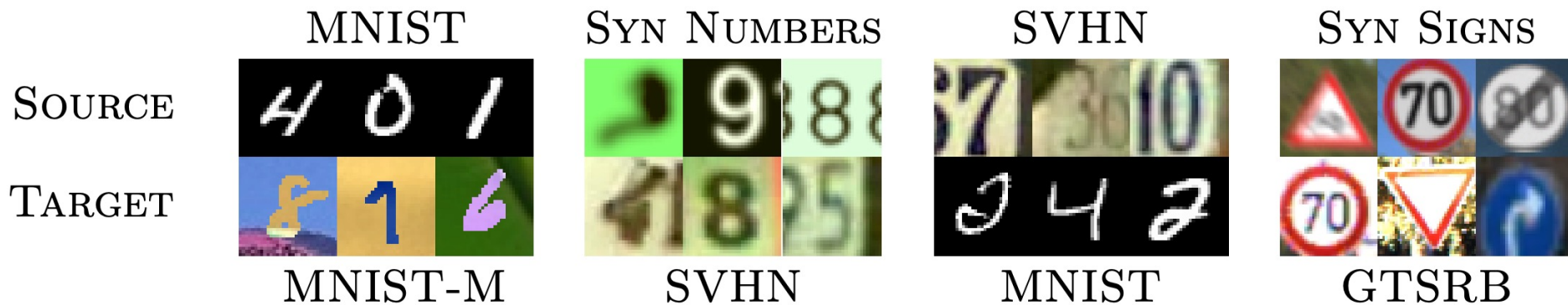
Transfer Learning: A Formal Definition

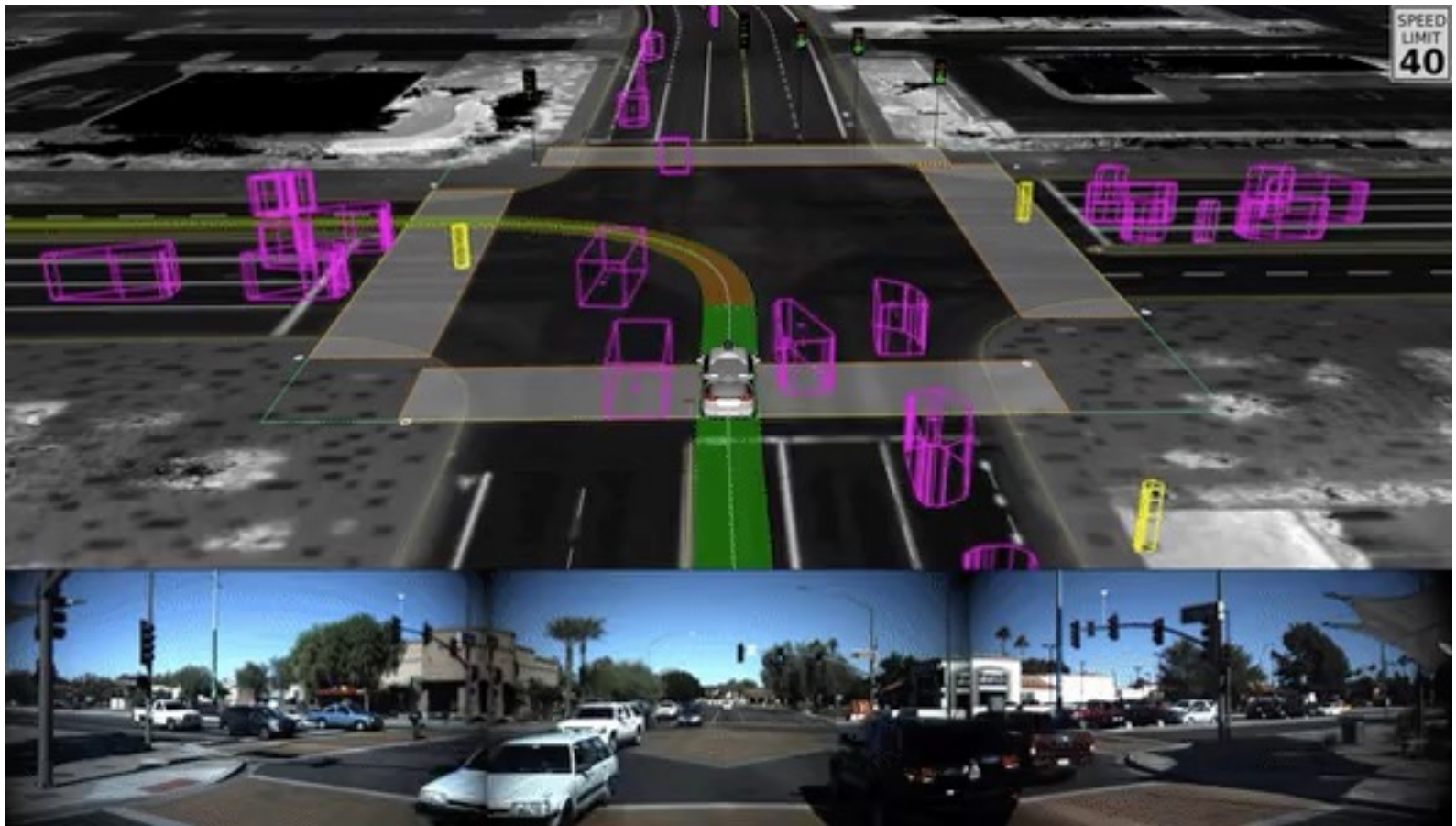
- The definition of transfer learning is given in terms of **domains** and **tasks**.
- A domain \mathbb{D} consists of a feature space \mathcal{X} and a probability distribution $P(X)$ where $X = \{x_1, x_2, \dots, x_n\} \in \mathcal{X}$
- A task \mathbb{T} consists of a label space \mathcal{Y} and a predictive function $f: \mathcal{X} \rightarrow \mathcal{Y}$

Given a source domain \mathbb{D}_s and a learning task \mathbb{T}_s , a target domain \mathbb{D}_t and a learning task \mathbb{T}_t , transfer learning aims to help improve the learning of the target predictive function $f_t(\cdot)$ for the target domain using the knowledge in \mathbb{D}_s and \mathbb{T}_s , where $\mathbb{D}_s \neq \mathbb{D}_t$ or $\mathbb{T}_s \neq \mathbb{T}_t$

Domain Adaptation: A Subfield of Transfer Learning

Domain adaptation is a specific scenario where the label space remains same, yet the probabilities between source and target domains change $P(X_s) \neq P(X_t)$



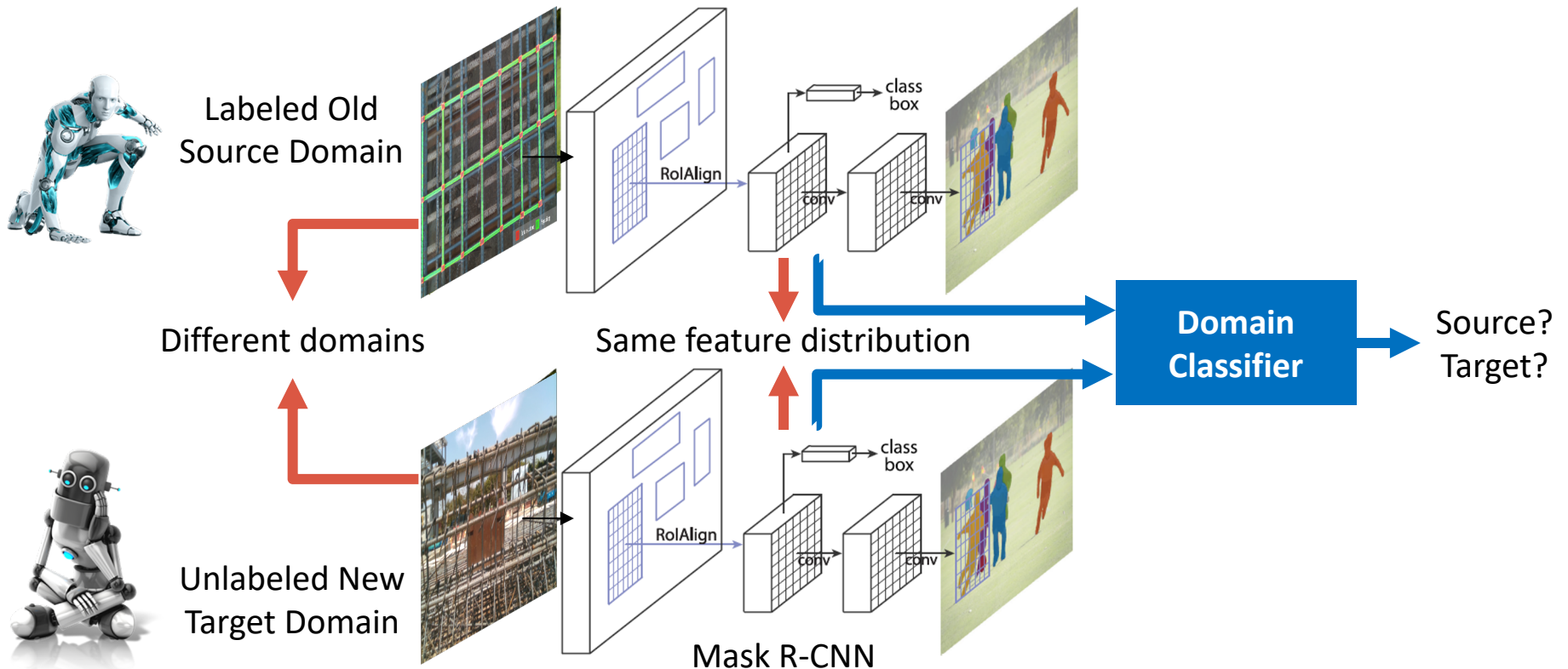


Waymo's Cars Drive 10 Million Miles (A Day in Virtual Space, 10 Years in Real Space)

<http://dipakramoliya.com/uncategorized/in-a-perilous-virtual-world-waymos-cars-drive-10-million-miles-a-day/>

Domain Adaptation for Rebar Image Segmentation

- **Domain variance** in rebar dataset:
rebar assembly, collecting time, shooting position
- **Domain adversarial training:** reduce discrepancy between domains
 - **Domain classifier:** try to distinguish between source and target domain
 - **Feature extractor:** try to fool domain classifier while training model

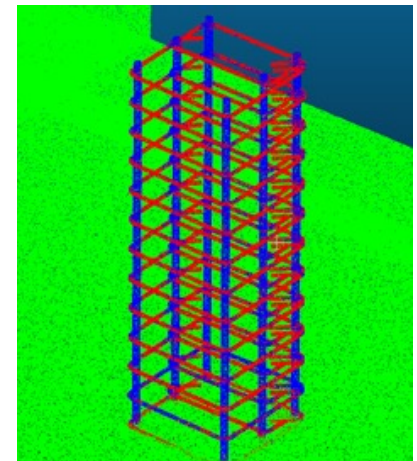
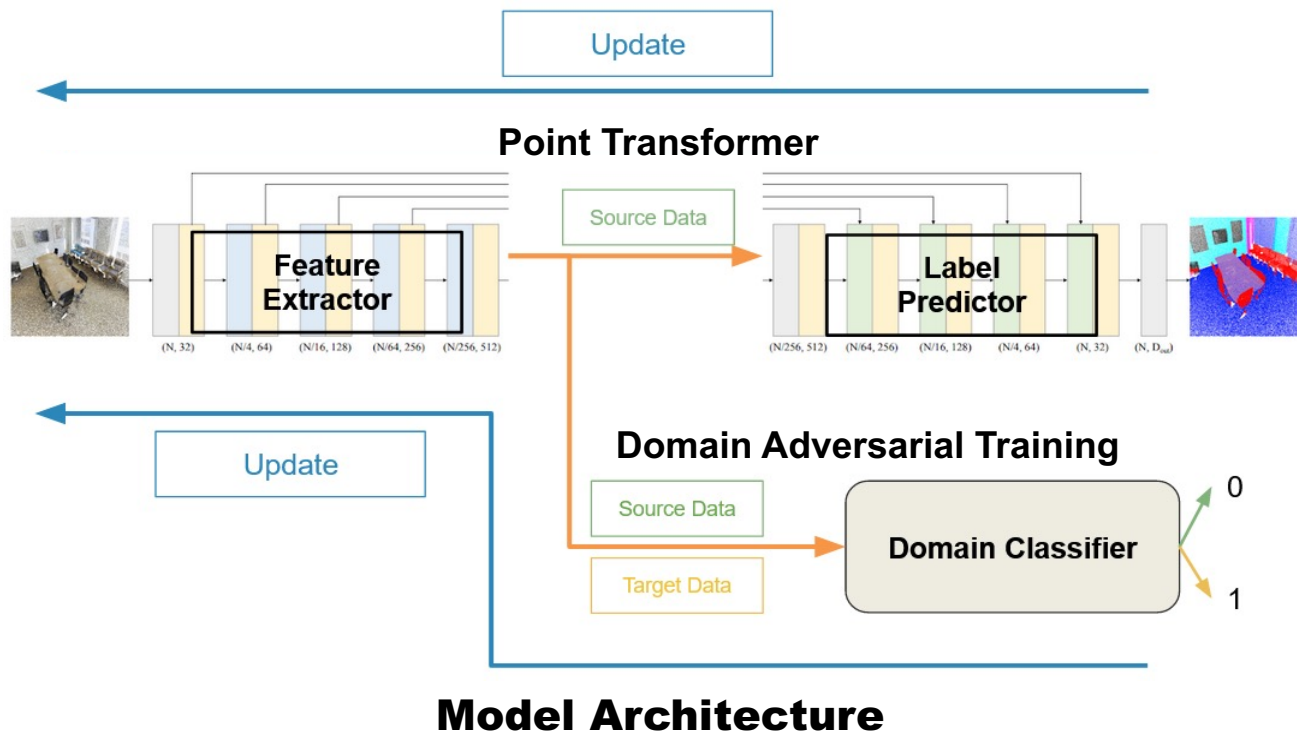


Domain Adaptation for Rebar Point Cloud Segmentation

Task: 3D semantic segmentation

Classes:

1. Background
2. Main rebars (主筋)
3. Ties (箍筋)



Source Data

- Virtual (parametric modeling by Revit)
- Labeled (automatic)



Target Data

- Real (SfM + MVS)
- Unlabeled

Transfer Learning for Image Classification

Transfer Learning for Image Classification: Rationale

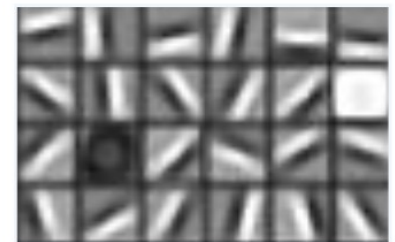
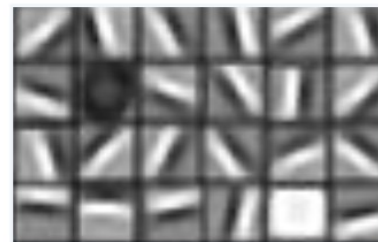
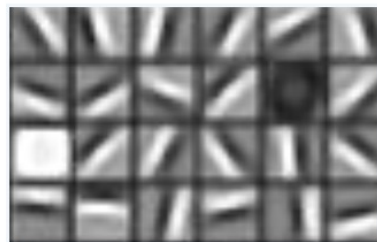
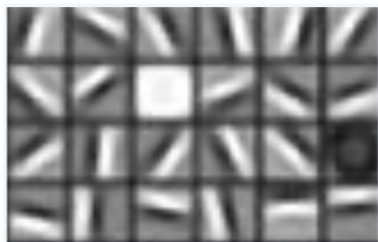
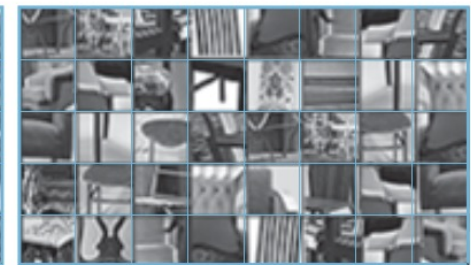
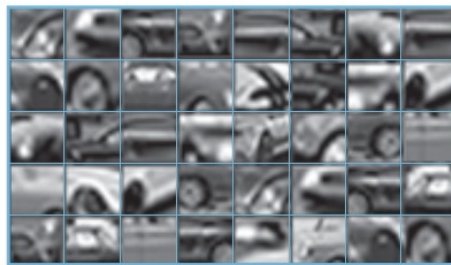
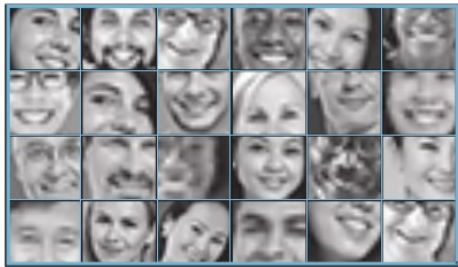
- A CNN learns the features in a dataset step by step **in increasing levels of complexity**. These are called feature maps. The deeper you go through the network layers, the more **image-specific** features are learned.

Faces

Cars

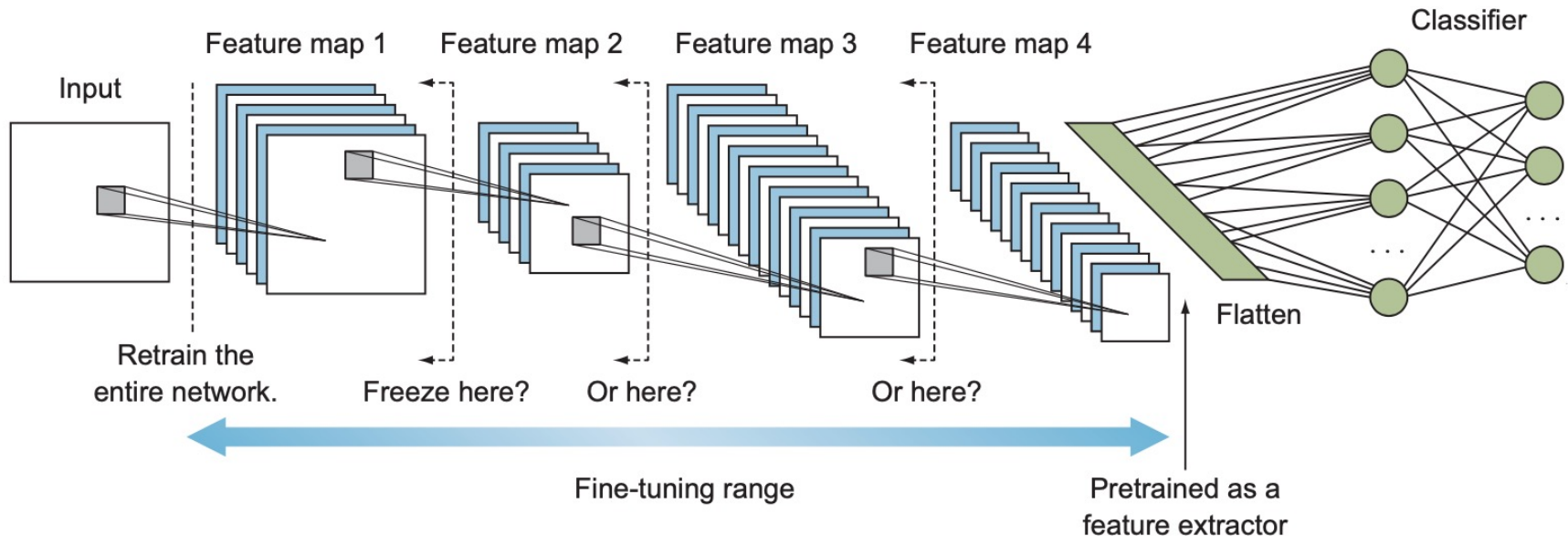
Elephants

Chairs



Transfer Learning for Image Classification: How

- Instead of starting from scratch, we can leverage a pretrained neural network (often a complex NN such as ResNet) and use their optimized parameters (weights) trained on a large dataset as a starting point to train our model on a smaller dataset for a given task.
- See CNN_Transfer_Learning_Part1.pdf

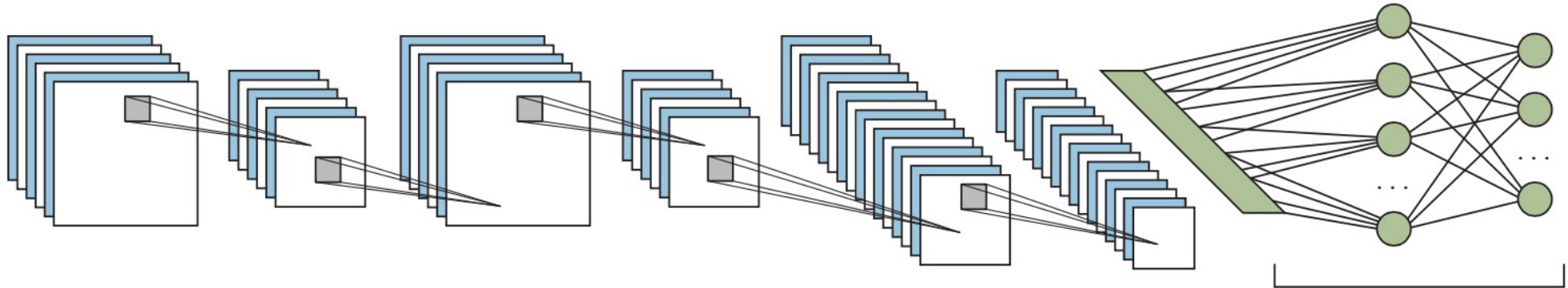


Transfer Learning Scenarios

Scenario	Size of the target data	Similarity of the original and new datasets	Approach
1	Small	Similar	Pretrained network as a feature extractor
2	Large	Similar	Fine-tune through the full network
3	Small	Very different	Fine-tune from activations earlier in the network
4	Large	Very different	Fine-tune through the entire network

- Scenario 3: see CNN_Transfer_Learning_Part2.pdf

Summary: Transfer Learning Scenarios and Strategies



Scenario #1: You have a small dataset that is similar to the source dataset.

Scenario #2: You have a large dataset that is similar to the source dataset.

Scenario #3: You have a small dataset that is different from the source dataset.

Scenario #4: You have a large dataset that is different from the source dataset.

Summary: Transfer Learning

- Given a source domain \mathbb{D}_s and a learning task \mathbb{T}_s , a target domain \mathbb{D}_t and a learning task \mathbb{T}_t , transfer learning aims to help improve the learning of the target predictive function $f_t(\cdot)$ for the target domain using the knowledge in \mathbb{D}_s and \mathbb{T}_s , where $\mathbb{D}_s \neq \mathbb{D}_t$ or $\mathbb{T}_s \neq \mathbb{T}_t$
- Domain adaptation is a subfield of transfer learning where the label space remains same, yet the probabilities between source and target domains change $P(X_s) \neq P(X_t)$
- Transfer learning migrates the knowledge learned from the source dataset to the target dataset, to save training time and computational cost and to improve generalization in target.
- The two main transfer learning approaches for image classification are using a pretrained network as a feature extractor, and fine-tuning.