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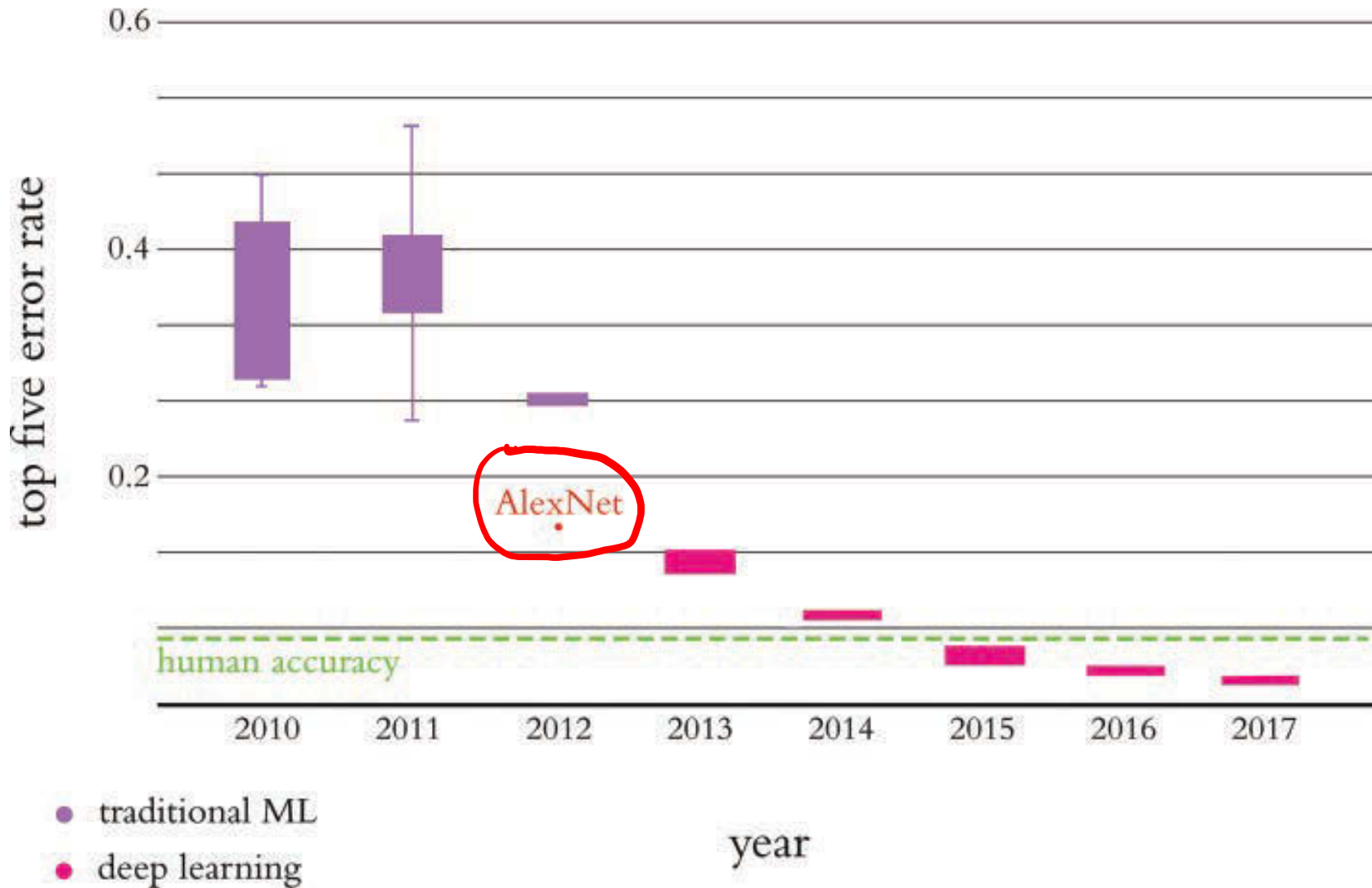


Deep Learning for Computer Vision (I)

Learning Objectives

- Learn the vast applications of deep learning for computer vision.
- Learn the basics of digital image representation
- Learn the workhorse: convolutional neural networks (CNNs)
- Learn the basic components and theories behind CNNs.

ILSVRC (the ImageNet Large Scale Visual Recognition Challenge)



沈向洋：以 Deep Learning 為核心的 Computer Vision，十年內將全面取代人眼 (2019.10.31 【與 AI 大師沈向洋博士對話】)



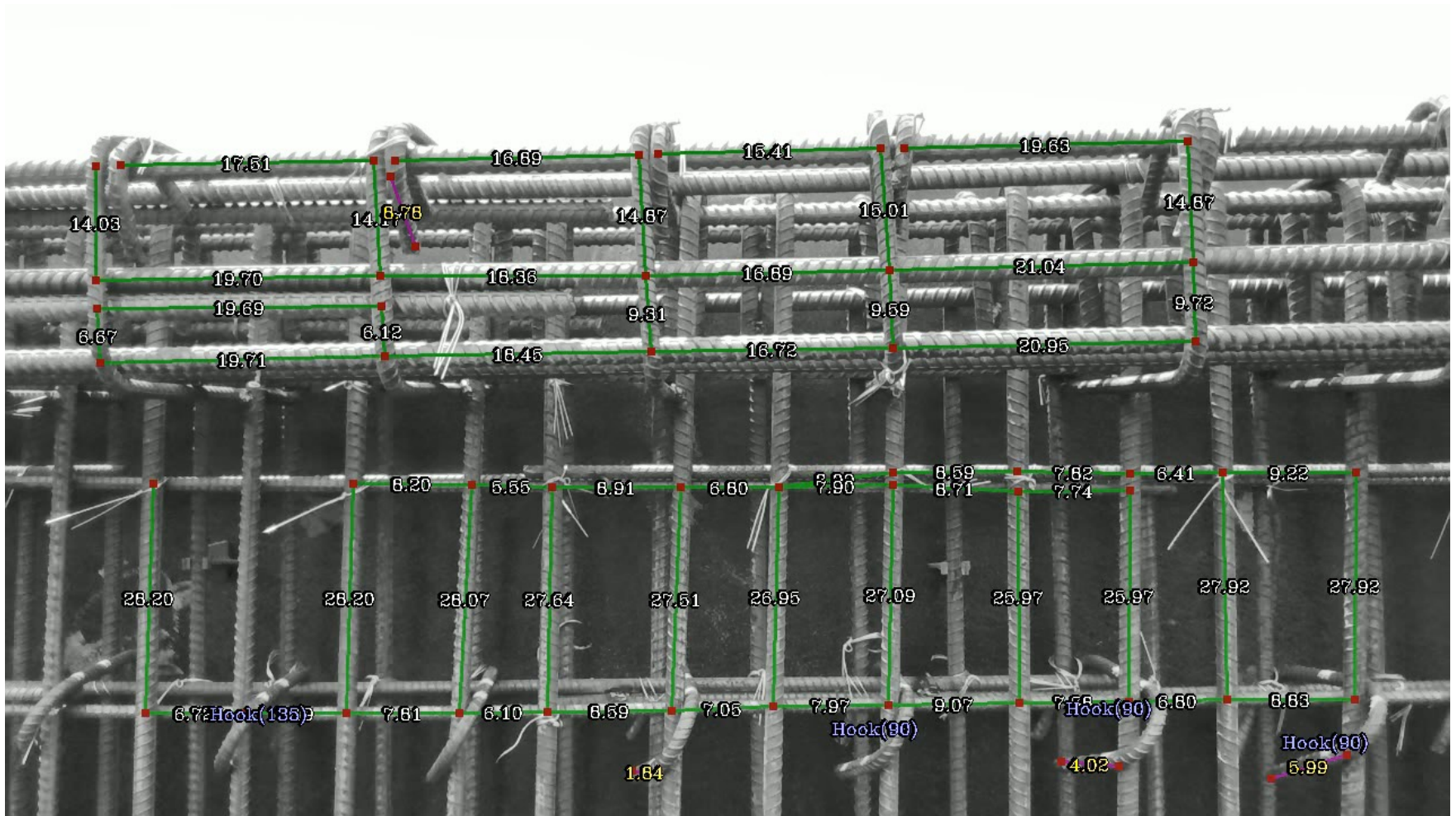
Tesla released what Autopilot's neural net can **see** (2020.01.31)



Apply cutting-edge research to train **deep neural networks** on problems ranging from perception to control. Our per-camera networks analyze raw images to perform **semantic segmentation**, **object detection** and **monocular depth estimation**. Our birds-eye-view networks take video from all cameras to output the **road layout**, **static infrastructure** and **3D objects** directly in the top-down view.

Our networks learn from the most complicated and diverse scenarios in the world, iteratively sourced from our fleet of nearly 1M vehicles in real time. A full build of Autopilot neural networks involves 48 networks that take 70,000 GPU hours to train 🔥. Together, they **output 1,000 distinct tensors (predictions)** at each timestep.

工地鋼筋全檢測



監造影像智慧增值：運用AI輔助現場工安管理

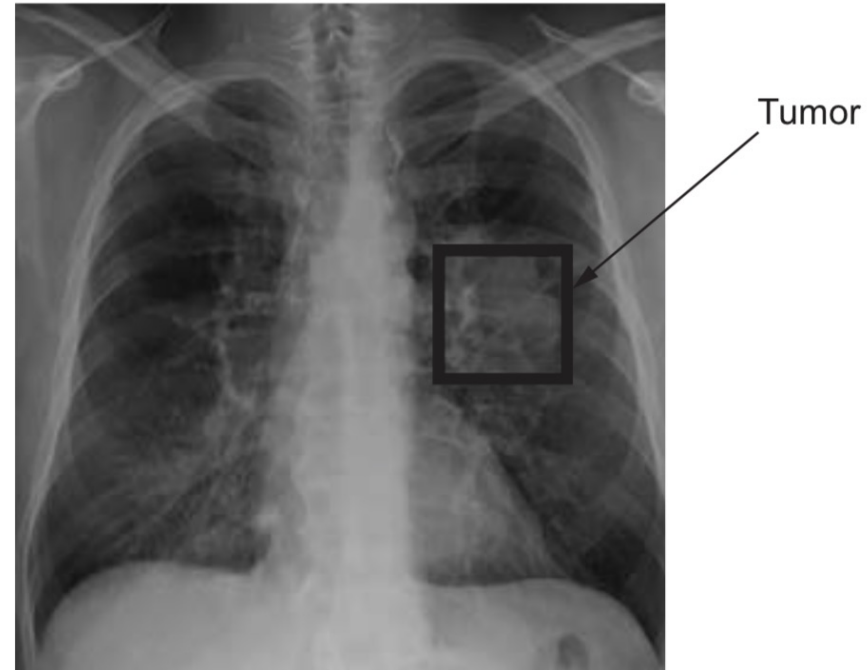


Source：趙志偉 研發工程師 中興工程顧問研發及資訊部

Applications of Computer Vision



CT scan



X-ray

Figure 1.5 Vision systems are now able to learn patterns in X-ray images to identify tumors in earlier stages of development.

Applications of Computer Vision



Figure 1.6 Vision systems can detect traffic signs with very high performance.

Applications of Computer Vision

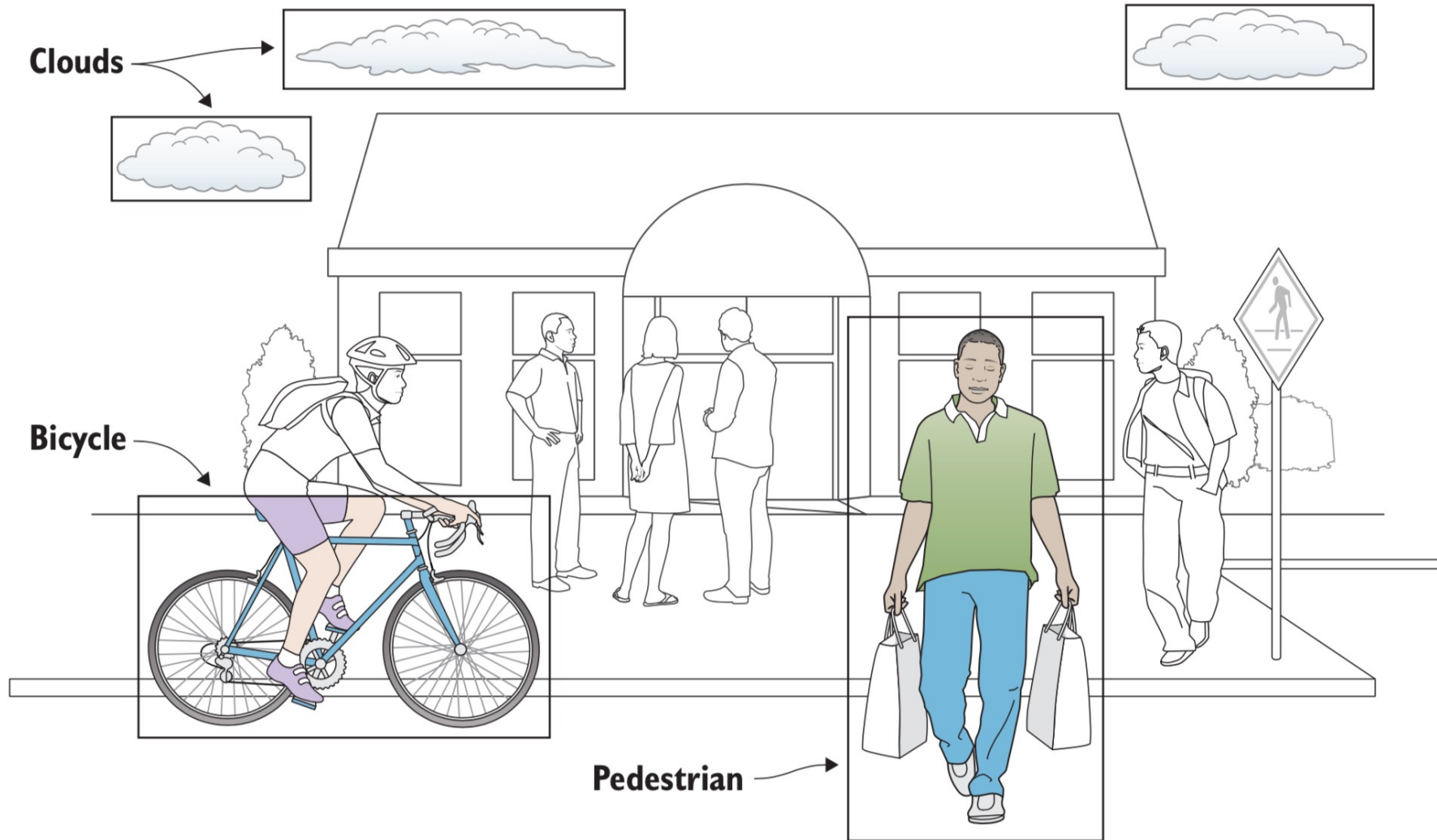


Figure 1.7 Deep learning systems can segment objects in an image.

Applications of Computer Vision

Original image

Style

Generated art



Figure 1.8 Style transfer from Van Gogh's *The Starry Night* onto the original image, producing a piece of art that feels as though it was created by the original artist

Applications of Computer Vision

This small blue bird has a short, pointy beak and brown on its wings.



This bird is completely red with black wings and a pointy beak.

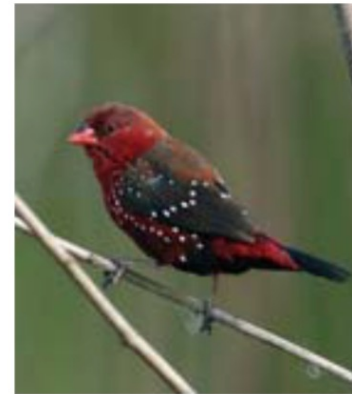
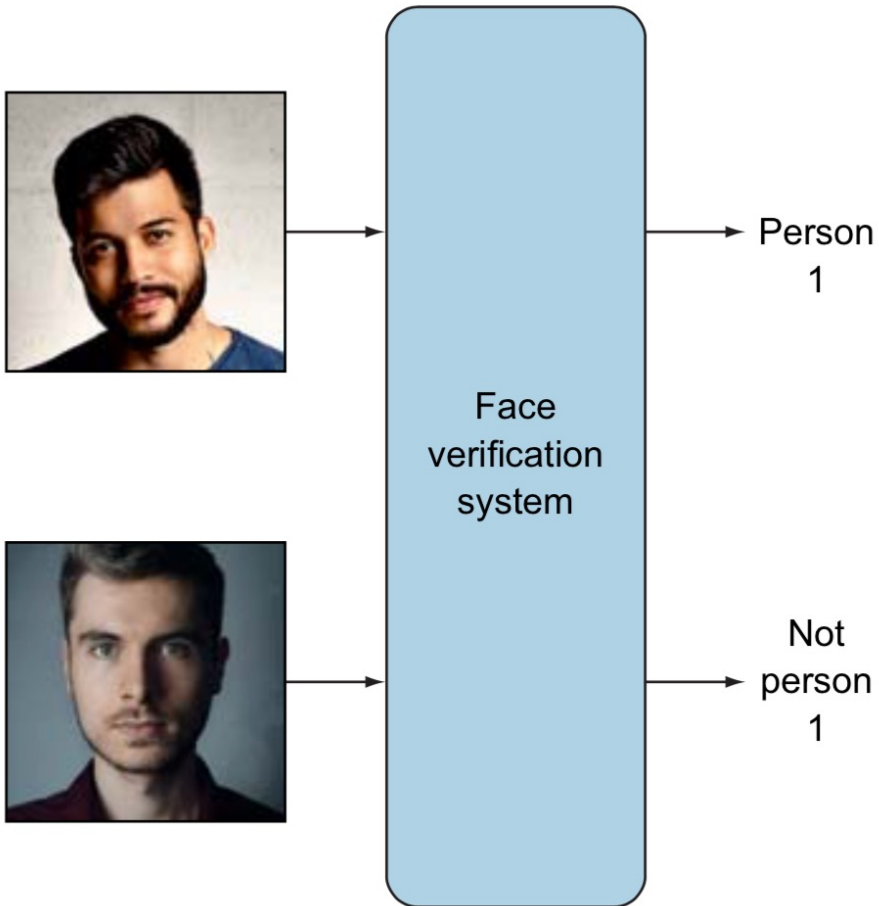


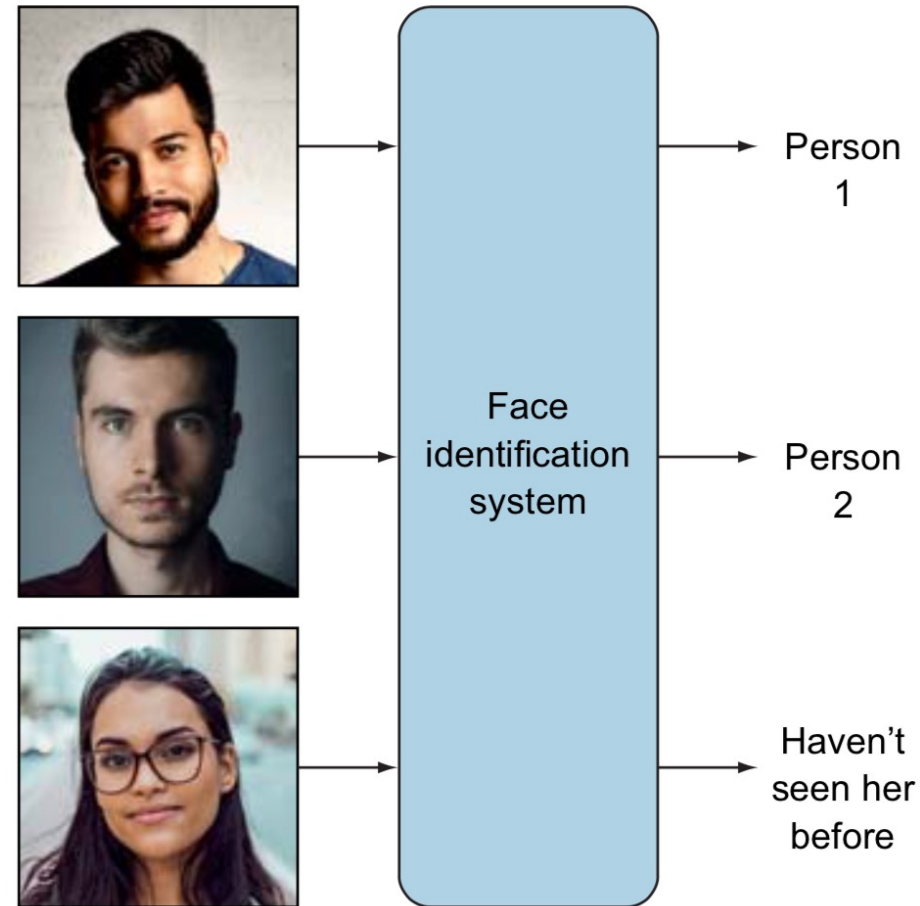
Figure 1.9 Generative adversarial networks (GANS) can create new, “made-up” images from a set of existing images.

Applications of Computer Vision

Face verification



Face identification



Query

Retrievals

Applications of Computer Vision

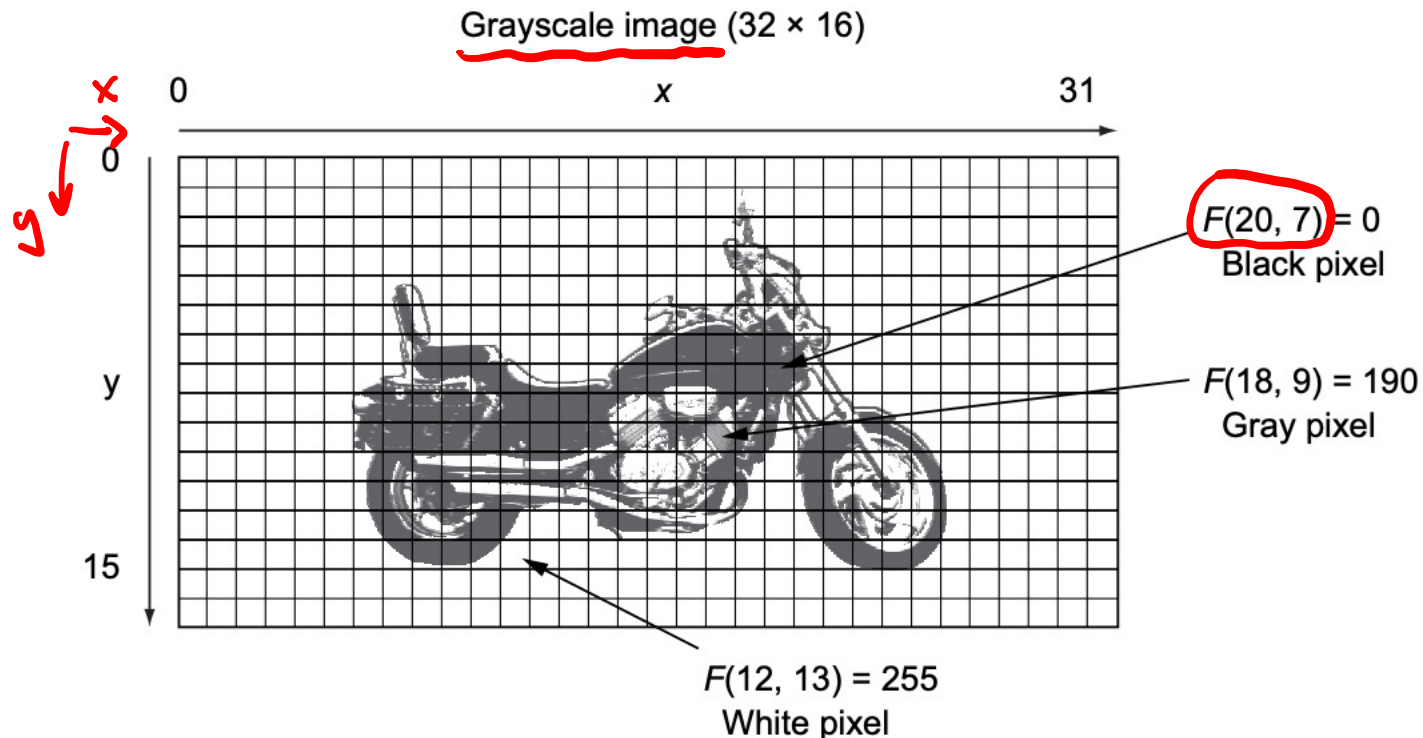


Image Representation 101

Image as a Function

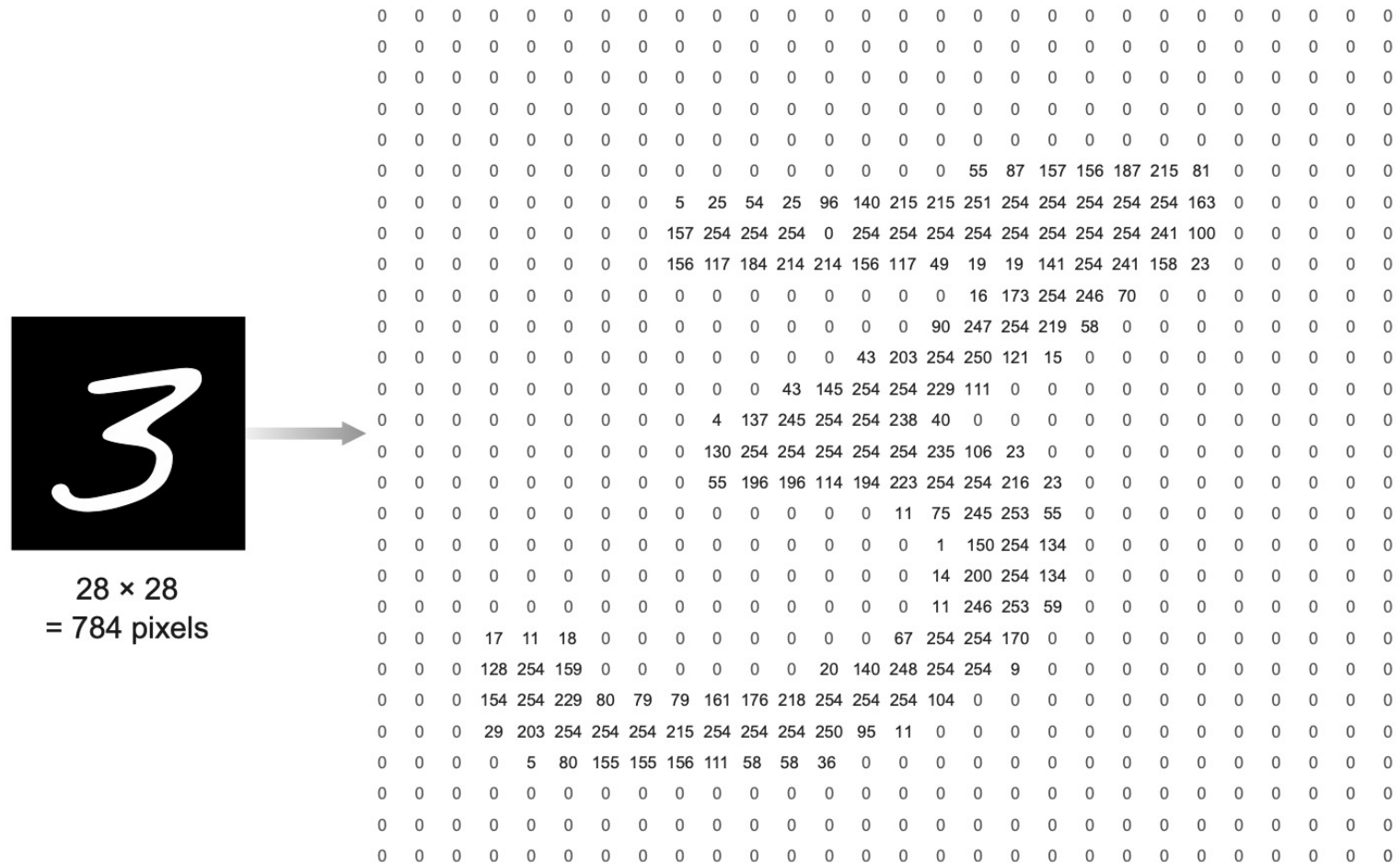
- An image can be represented as a function of two variables x and y , which define a two-dimensional area. A digital image is made of a grid of pixels.
- The **pixel** is the raw building block of an image. Every image consists of a set of pixels in which their values represent the **intensity** of light that appears in a given place in the image.

0..255



How Computer See Image

- To a computer, the image looks like a 2D matrix of the pixels' values, which represent intensities. There is no context here, just a massive pile of data.



How Computer See Color Image

- Color images have three channels (red, green, and blue) and are often represented by three matrices: one represents the intensity of red in the pixel, one represents green, and one represents blue

Color image

RGB channels

$$F(0, 0) = [11, 102, 35]$$


Channel 3

Blue intensity values

Channel 2

Green intensity
values

Channel 1
Red intensity
values

Channel 3

Blue intensity values

2

intensity

35	165	163	165	158	...
166	166	164	166	159	...
156	158	162	165	159	...
102	169	167	169	169	...
170	170	168	170	170	...
160	162	166	169	170	...
11	158	156	158	158	...
159	159	157	159	159	...
149	151	155	158	159	...
146	146	149	153	158	...
145	143	143	148	158	...
...

Image Flattening

- We often need to do image flattening when we use MLP for classification.

To help visualize the flattened input vector, let's look at a much smaller matrix (4, 4):

Blue	White	White	White
Blue	Blue	Blue	White
Blue	Blue	White	Blue
Blue	White	Blue	Blue

The input (x) is a flattened vector with the dimensions (1, 16):

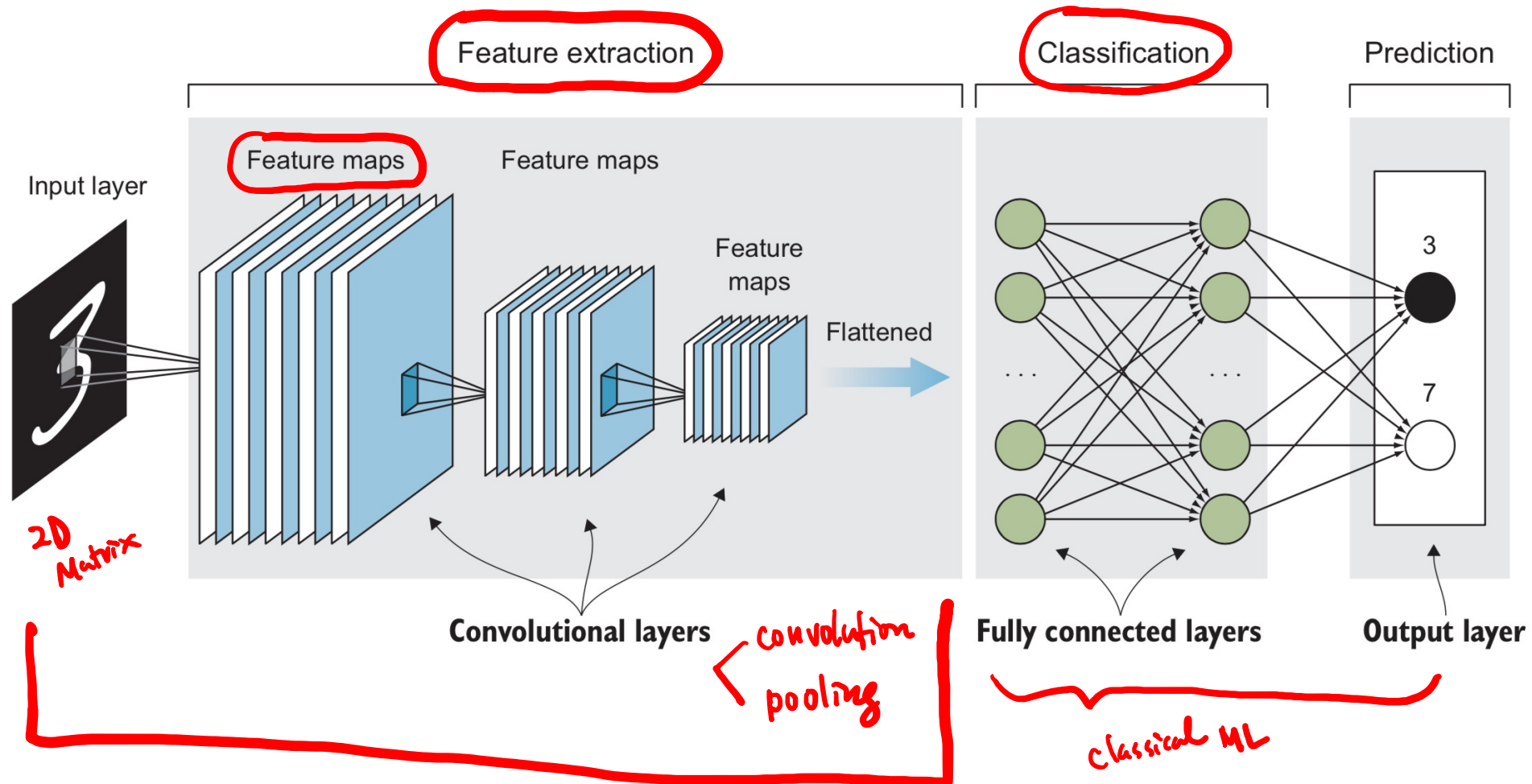
X_1	X_2	X_3	X_4	X_5	X_6	X_7	X_8	X_9	X_{10}	X_{11}	X_{12}	X_{13}	X_{14}	X_{15}	X_{16}
Row 1				Row 2				Row 3				Row 4			

So, if we have pixel values of 0 for black and 255 for white, the input vector will be as follows:

Input = [0, 255, 255, 255, 0, 0, 0, 255, 0, 0, 255, 0, 0, 255, 0, 0]

Convolutional Neural Networks (CNNs) : An Overview

High-level architecture of CNNs: **input layer**, **convolutional layers**, **fully connected layers**, and **output prediction**



DNNs vs. CNNs: See CNN_MNIST.ipynb

Layer (type)	Output Shape	Param #
dense (Dense)	(None, 784)	615440
dense_1 (Dense)	(None, 10)	7850
Total params: 623,290		
Trainable params: 623,290		
Non-trainable params: 0		

Layer (type)	Output Shape	Param #
conv2d_3 (Conv2D)	(None, 26, 26, 32)	<u>320</u>
max_pooling2d_2 (MaxPooling2)	(None, 13, 13, 32)	0
conv2d_4 (Conv2D)	(None, 11, 11, 64)	<u>18496</u>
max_pooling2d_3 (MaxPooling2)	(None, 5, 5, 64)	0
conv2d_5 (Conv2D)	(None, 3, 3, 64)	<u>36928</u>
flatten_1 (Flatten)	(None, 576)	0
dense_4 (Dense)	(None, 64)	36928
dense_5 (Dense)	(None, 10)	650
Total params: 93,322		
Trainable params: 93,322		
Non-trainable params: 0		

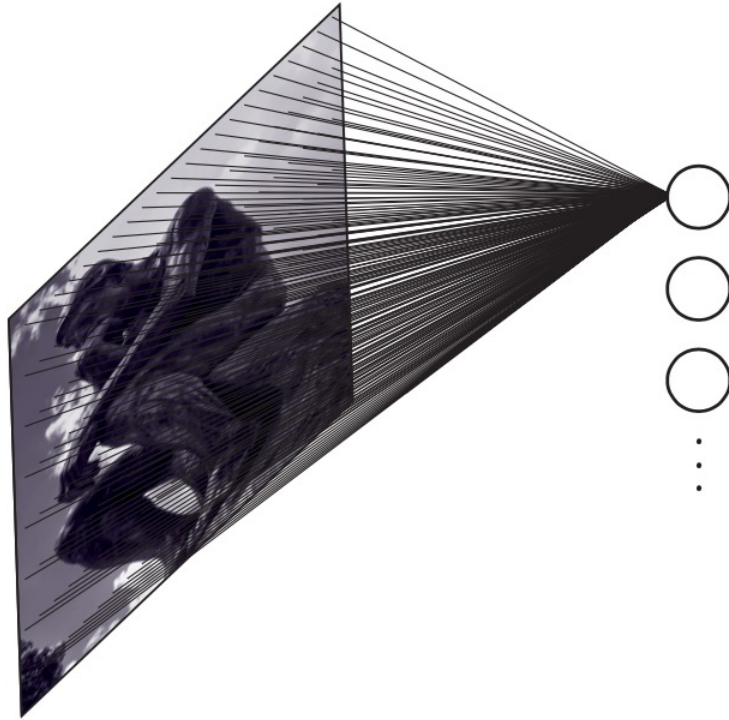
784

- * CNNs yield better results with less training parameters
- * DNNs and CNNs do not usually yield comparable results; MNIST dataset is an exception. In messy real-world image data, CNNs truly outshine DNNs.

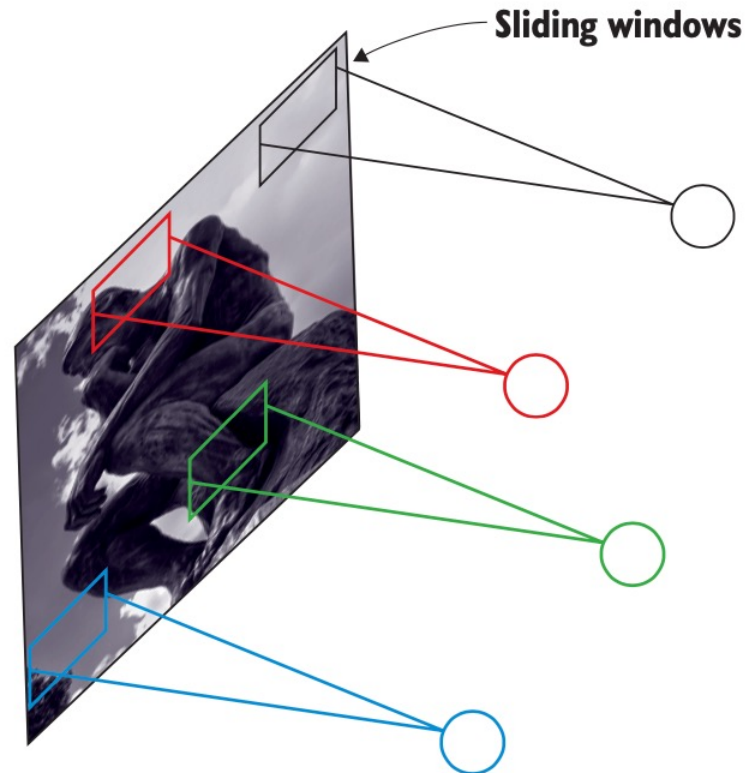
Fundamental Difference between DNNs and CNNs

Global vs. Local

Fully connected neural net



Locally connected neural net

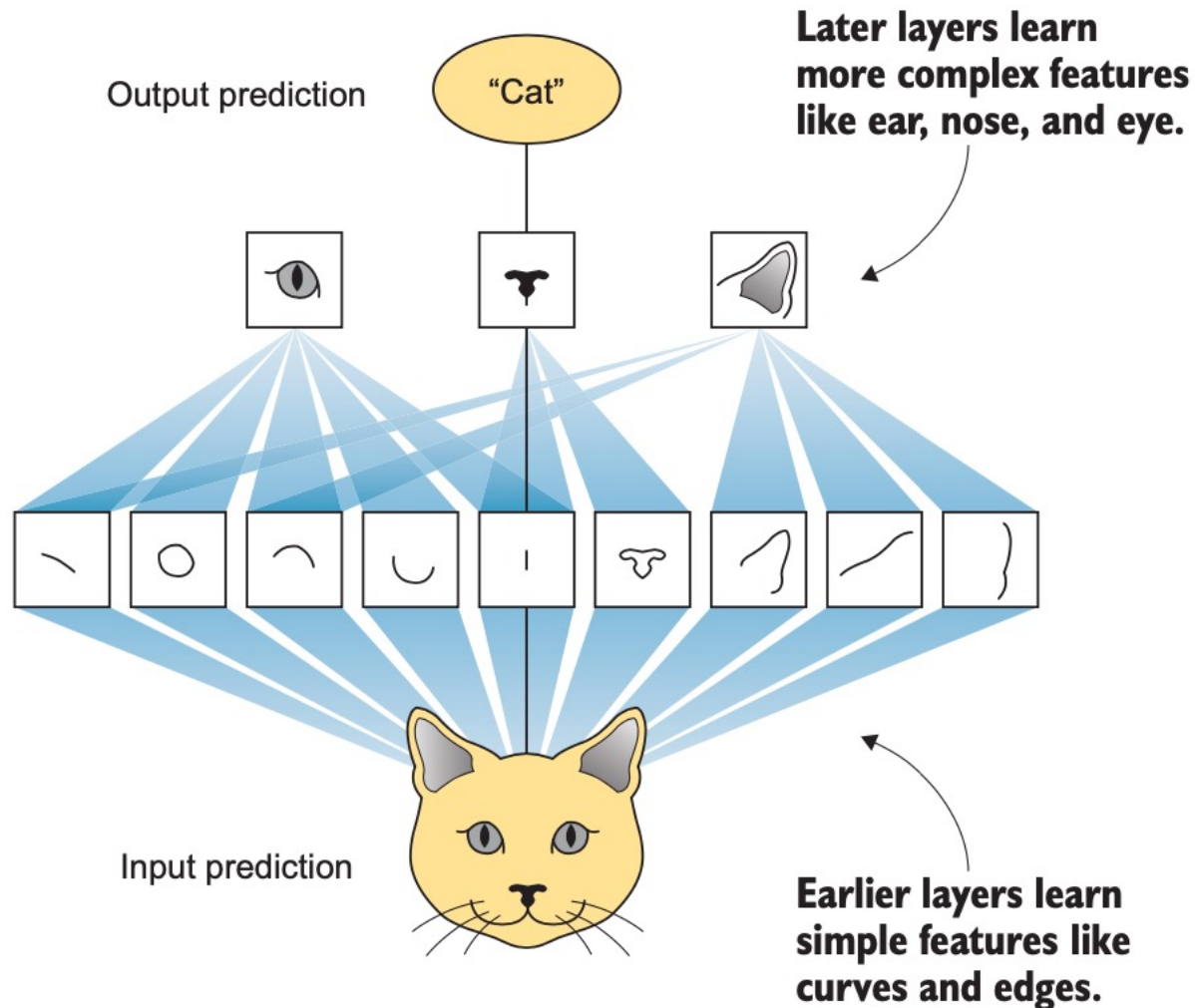


**The patterns CNNs learn are translation invariant.
CNNs can learn spatial hierarchies of patterns.**

CNNs learn the image features through its layers.

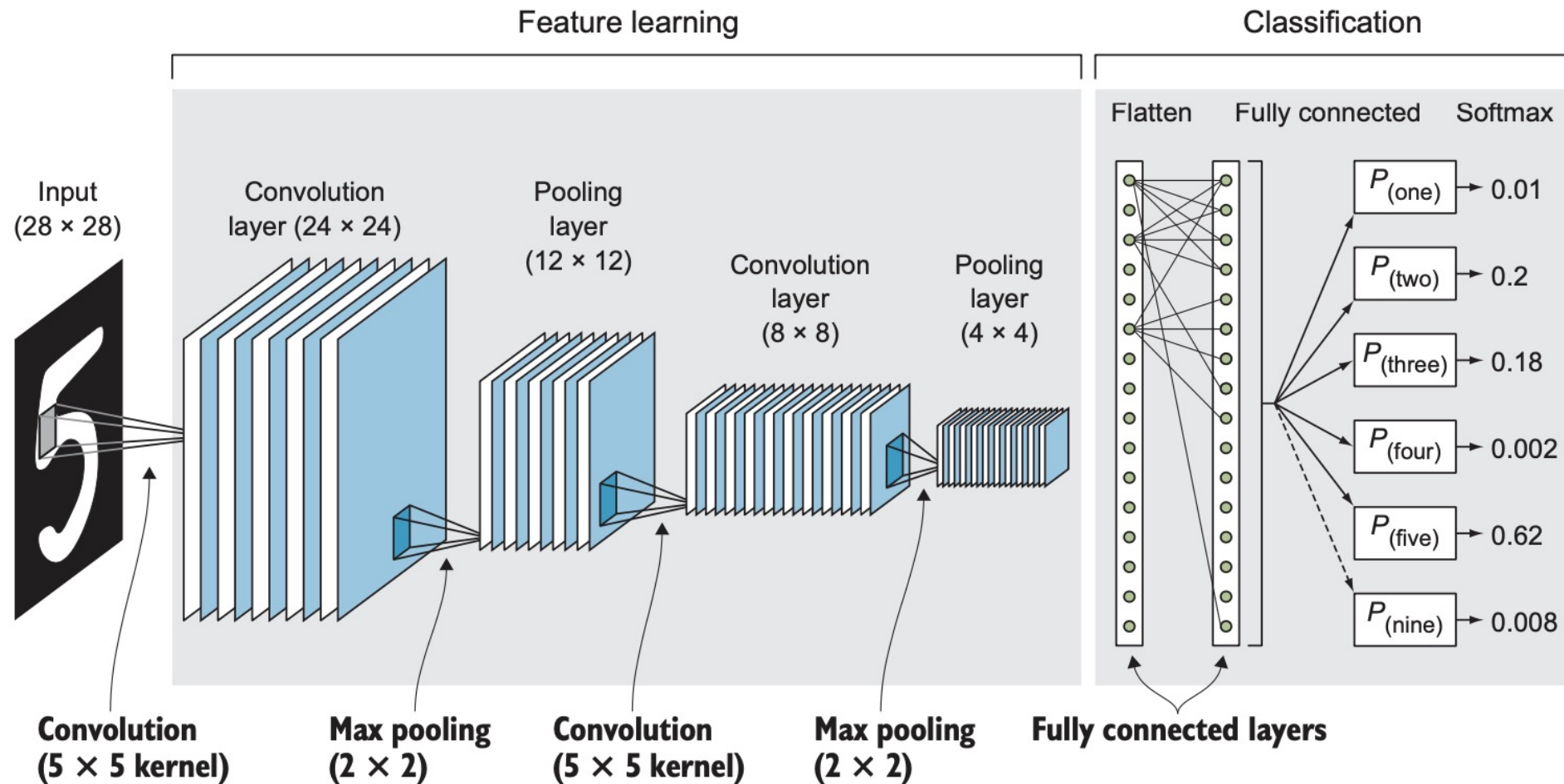
The patterns CNNs learn are translation invariant.

CNNs can learn spatial hierarchies of patterns.



Basic Components of Convolutional Neural Networks (CNNs)

The basic components of convolutional networks are **convolutional layers** and **pooling layers** to perform **feature extraction**, and **fully connected layers** for classification



Basic components of CNNs: theoretical minimum and example

- The phrase “theoretical minimum” is taken from a very successful book series written by Leonard Susskind, a great physicist at Stanford University.
- “Theoretical minimum” means just the minimum theories and equations you need to know in order to proceed to the next level.
- See CNN_Basics.pdf