

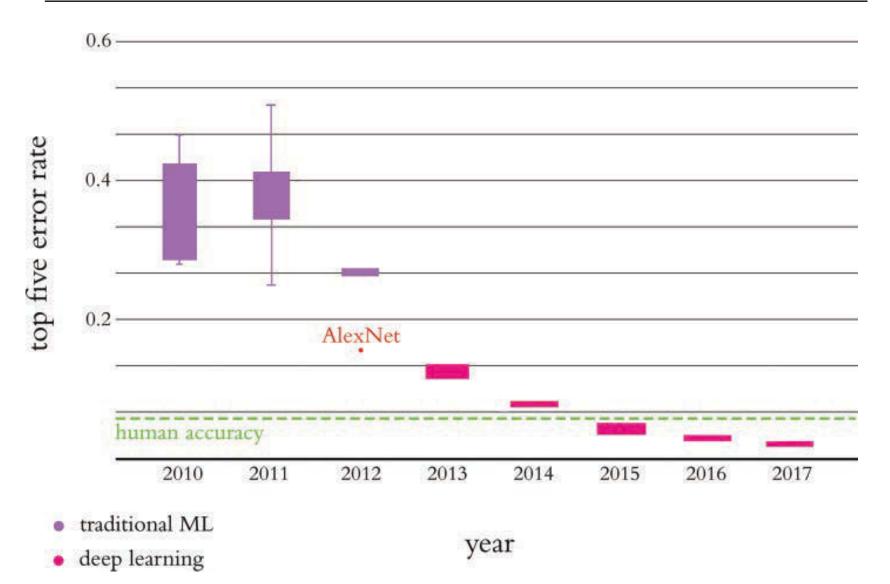
https://www.sli.do/ #073374

Deep Learning for Computer Vision (I)

Learning Objectives

- Learn the vast applications of deep learning for computer vision.
- Learn the basics of digital image representation
- Learn the workhorse: convolutional neural networks (CNNs)
- Learn the basic components and theories behind CNNs.

ILSVRC (the ImageNet Large Scale Visual Recognition Challenge)



沈向洋:以 Deep Learning 為核心的 Computer Vision,十年內將全面取代人眼 (2019.10.31 【與 AI大師沈向洋博士對話】)



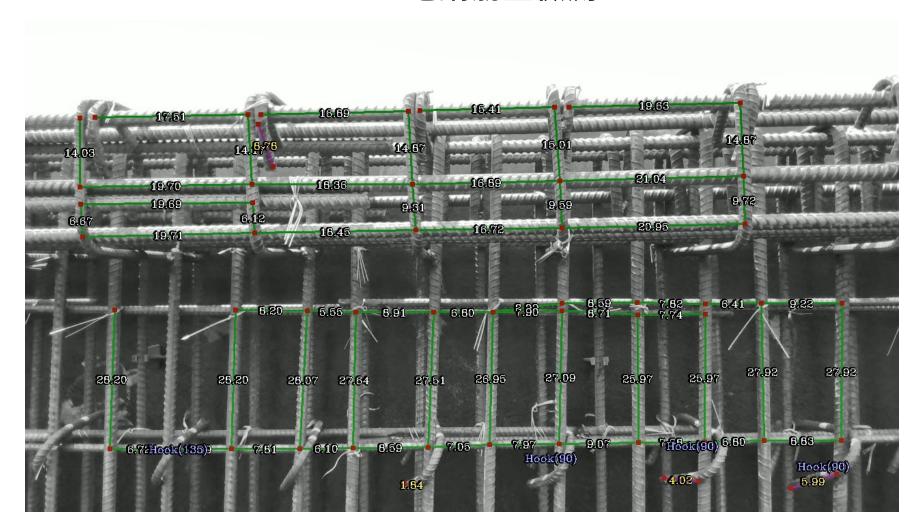
Tesla released what Autopilot's neural net can see (2020.01.31)



Apply cutting-edge research to train **deep neural networks** on problems ranging from
perception to control. Our per-camera
networks analyze <u>raw images</u> to perform **semantic segmentation**, **object detection** and **monocular depth estimation**. Our birds-eyeview networks take <u>video from all cameras</u> to
output the **road layout**, **static infrastructure**and **3D objects** directly in the top-down view.

Our networks learn from the most complicated and diverse scenarios in the world, iteratively sourced from our fleet of nearly 1M vehicles in real time. A full build of Autopilot neural networks involves 48 networks that take 70,000 GPU hours to train . Together, they output 1,000 distinct tensors (predictions) at each timestep.

工地鋼筋全檢測



監造影像智慧加值:運用AI輔助現場工安管理



Source: 趙志偉 研發工程師 中興工程顧問研發及資訊部

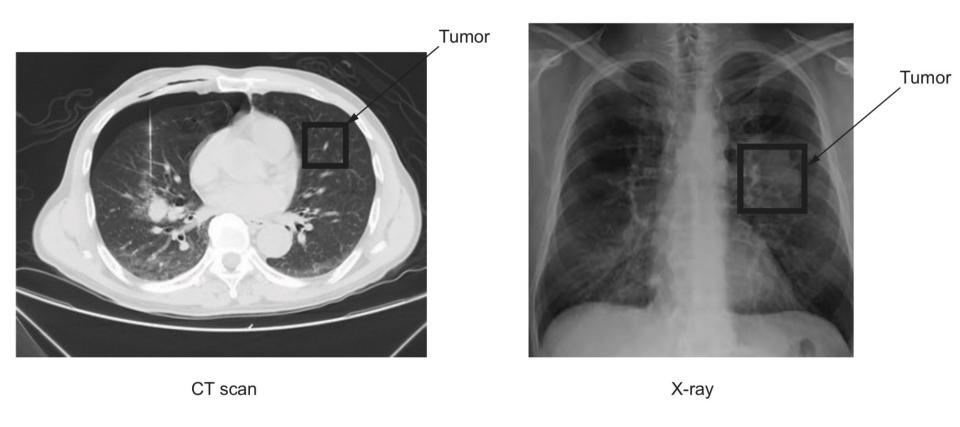


Figure 1.5 Vision systems are now able to learn patterns in X-ray images to identify tumors in earlier stages of development.



Figure 1.6 Vision systems can detect traffic signs with very high performance.

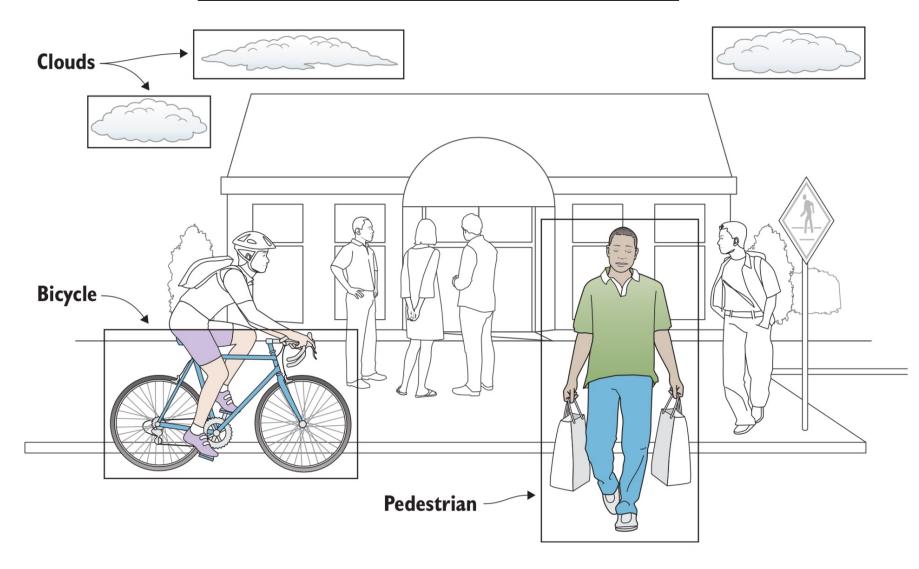


Figure 1.7 Deep learning systems can segment objects in an image.



Figure 1.8 Style transfer from Van Gogh's *The Starry Night* onto the original image, producing a piece of art that feels as though it was created by the original artist

This small blue bird has a short, pointy beak and brown on its wings.









This bird is completely red with black wings and a pointy beak.

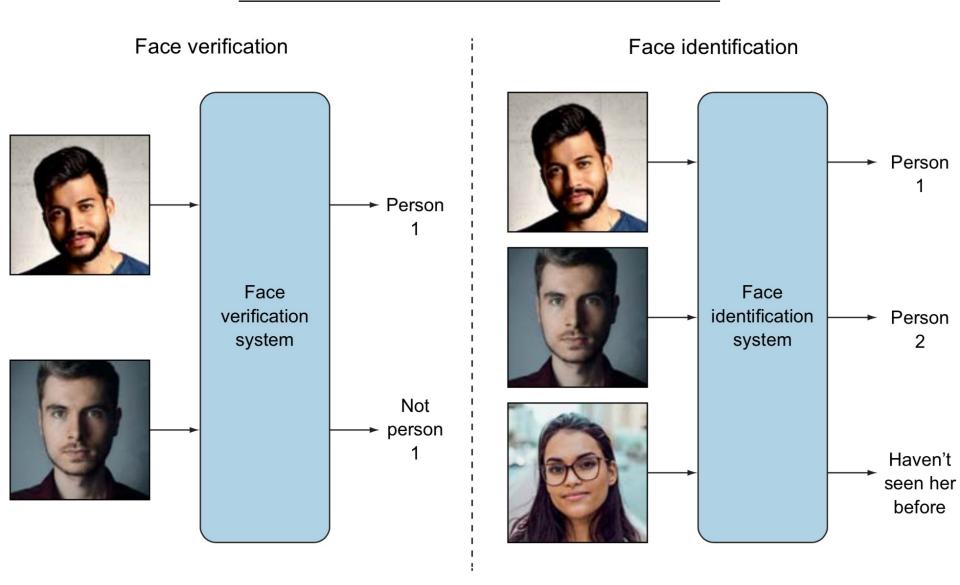




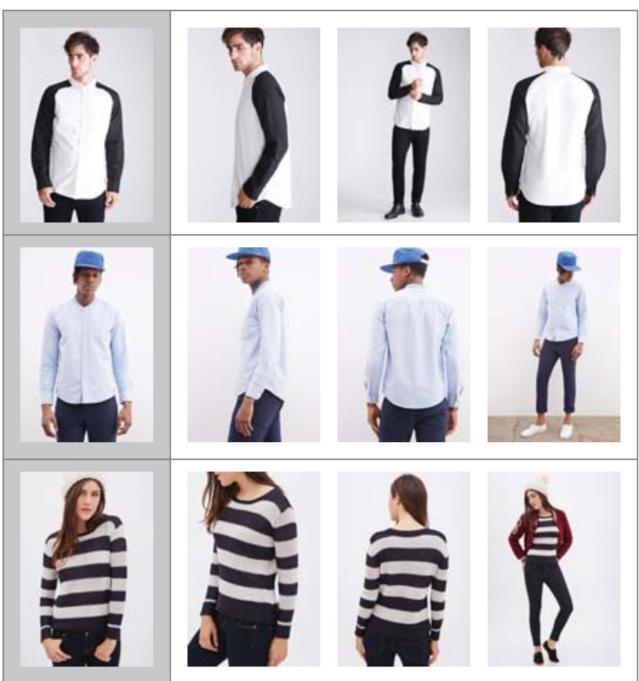




Figure 1.9 Generative adversarial networks (GANS) can create new, "made-up" images from a set of existing images.



Query Retrievals



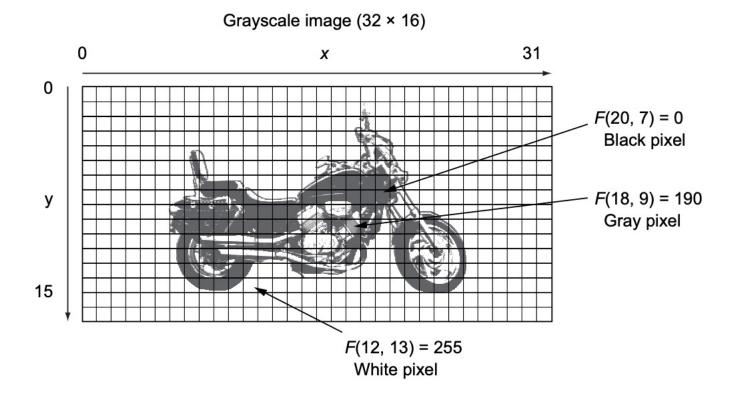
Applications of Computer Vision

M. Elgendy (2020) Deep Learning for Vision System.

Image Representation 101

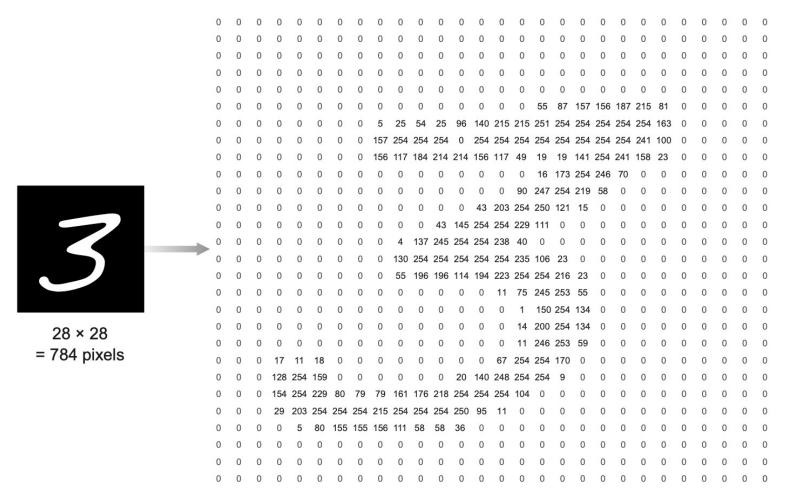
Image as a Function

- An image can be represented as <u>a function of two variables x and y</u>, which define a two-dimensional area. A digital image is made of a grid of pixels.
- The *pixel* is the raw building block of an image. Every image consists of a set of pixels in which their values represent the *intensity* of light that appears in a given place in the image.



How Computer See Image

• To a computer, the image looks like a 2D matrix of the pixels' values, which represent intensities. There is no context here, just a massive pile of data.



How Computer See Color Image

• Color images have three channels (red, green, and blue) and are often represented by three matrices: one represents the intensity of red in the pixel, one represents green, and one represents blue

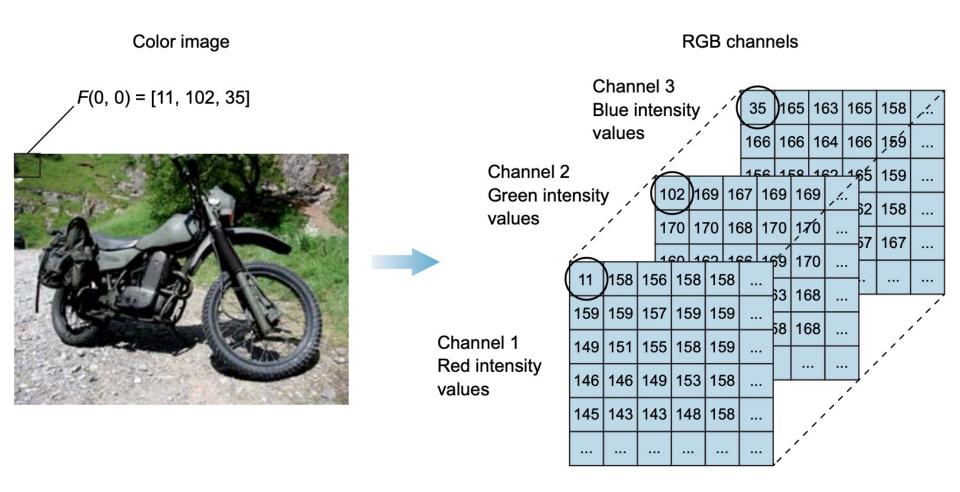
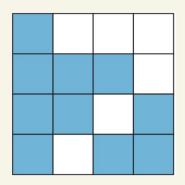


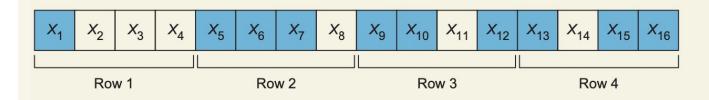
Image Flattening

• We often need to do image flattening when we use MLP for classification.

To help visualize the flattened input vector, let's look at a much smaller matrix (4, 4):



The input (x) is a flattened vector with the dimensions (1, 16):

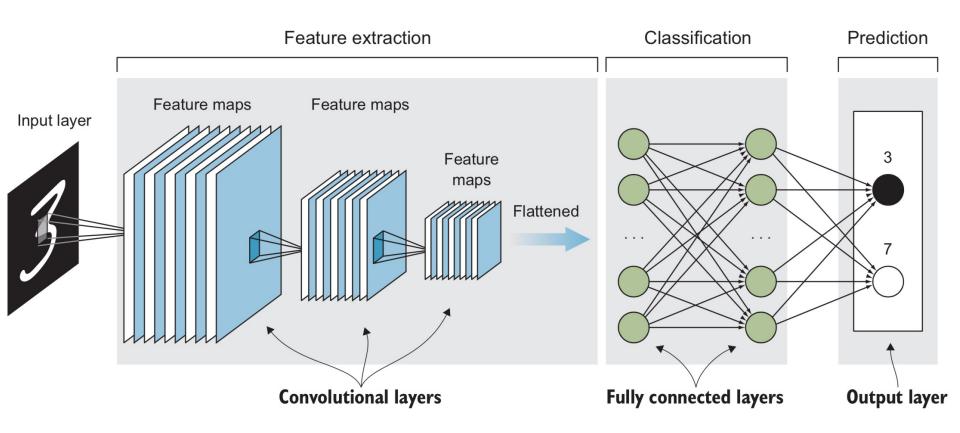


So, if we have pixel values of 0 for black and 255 for white, the input vector will be as follows:

Input = [0, 255, 255, 255, 0, 0, 0, 255, 0, 0, 255, 0, 0, 255, 0, 0]

Convolutional Neural Networks (CNNs): An Overview

High-level architecture of CNNs: input layer, convolutional layers, fully connected layers, and output prediction



DNNs vs. CNNs: See CNN_MNIST.ipynb

Layer (type)	Output Shape	Param #
dense (Dense)	(None, 784)	615440
dense_1 (Dense)	(None, 10)	7850

Total params: 623,290 Trainable params: 623,290 Non-trainable params: 0

Layer (type)	Output	Shape 	Param #
conv2d_3 (Conv2D)	(None,	26, 26, 32)	320
max_pooling2d_2 (MaxPooling2	(None,	13, 13, 32)	0
conv2d_4 (Conv2D)	(None,	11, 11, 64)	18496
max_pooling2d_3 (MaxPooling2	(None,	5, 5, 64)	0
conv2d_5 (Conv2D)	(None,	3, 3, 64)	36928
flatten_1 (Flatten)	(None,	576)	0
dense_4 (Dense)	(None,	64)	36928
dense_5 (Dense)	(None,	10)	650

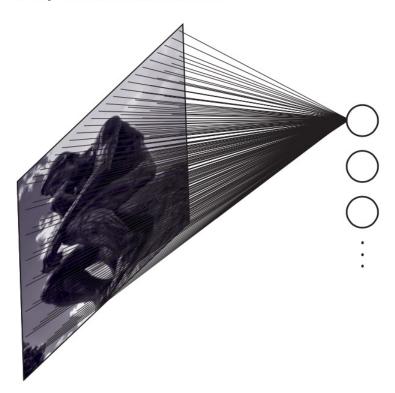
Total params: 93,322 Trainable params: 93,322 Non-trainable params: 0 CNNs yield better results with less training parameters

DNNs and CNNs do not usually yield comparable results; MNIST dataset is an exception. In messy real-world image data, CNNs truly outshine DNNs.

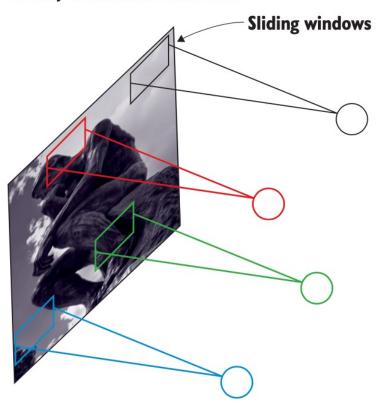
Fundamental Difference between DNNs and CNNs

Global vs. Local

Fully connected neural net



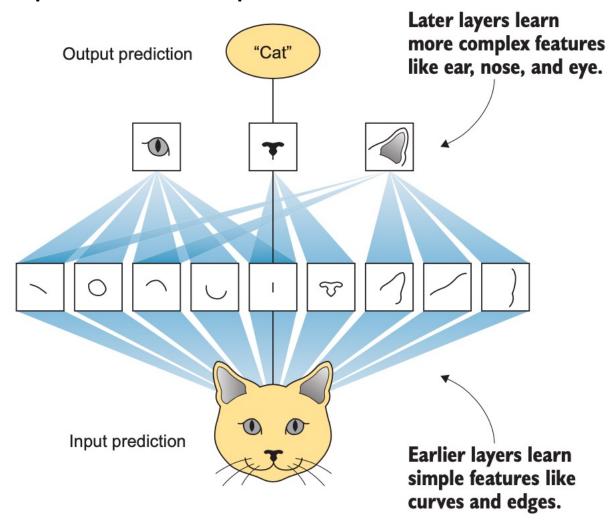
Locally connected neural net



The patterns CNNs learn are translation invariant. CNNs can learn spatial hierarchies of patterns.

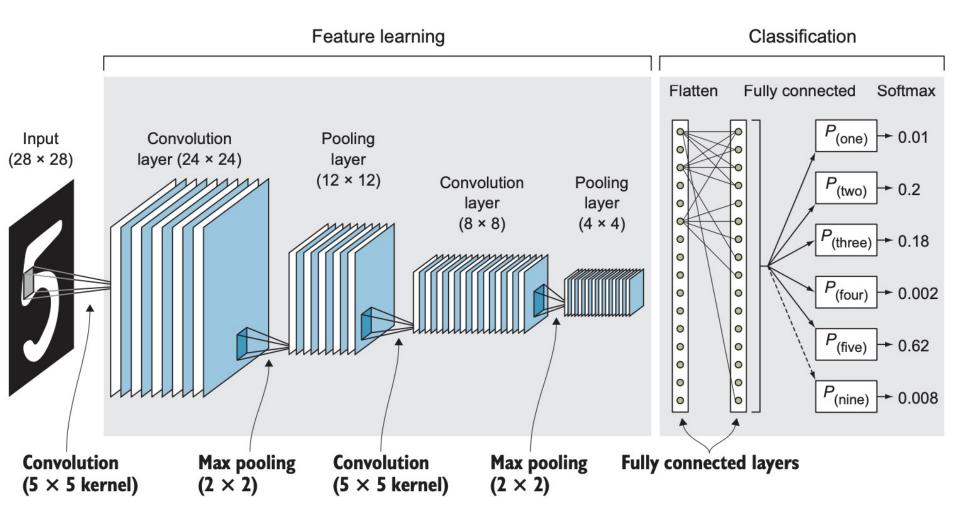
CNNs learn the image features through its layers.

The patterns CNNs learn are translation invariant. CNNs can learn spatial hierarchies of patterns.



Basic Components of Convolutional Neural Networks (CNNs)

The basic components of convolutional networks are convolutional layers and pooling layers to perform feature extraction, and fully connected layers for classification



Basic components of CNNs: theoretical minimum and example

- The phrase "theoretical minimum" is taken from a very successful book series written by Leonard Susskind, a great physicist at Stanford University.
- "Theoretical minimum" means just the minimum theories and equations you need to know in order to proceed to the next level.
- See CNN_Basics.pdf